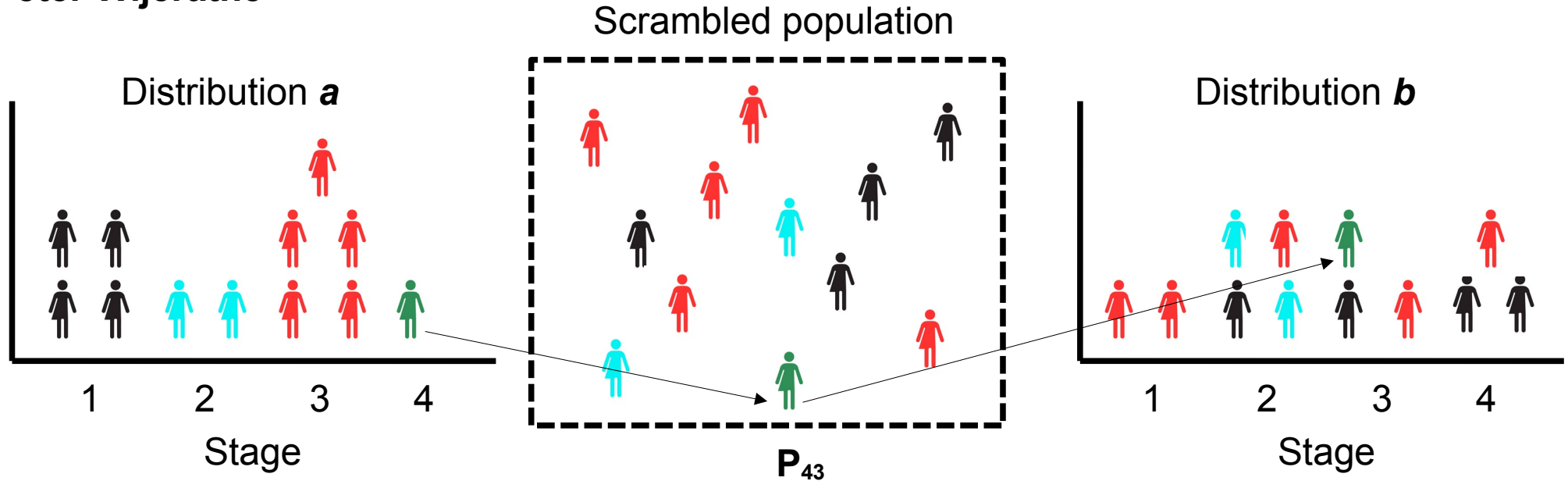


A probabilistic perspective on modelling disease progression (with some optimal transport)

Sussex Maths seminar
20/03/25

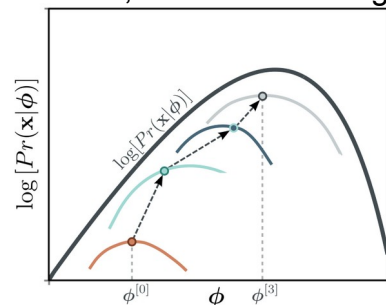
Peter Wijeratne



Our research: bridging computer and life sciences

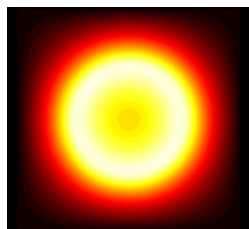
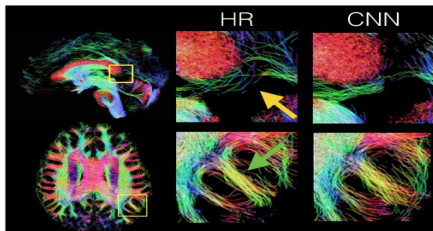
Informatics

* Prince, S. Understanding Deep Learning. MIT Press



**Machine
learning &
statistics**

**Image
processing**



**Physics-
guided
modelling**

**Sussex AI
Centre**

Life sciences



Neuroscience

Clinical imaging sciences



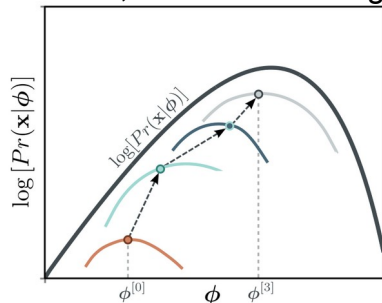
**Clinical and translational
research**



Our research: bridging computer and life sciences

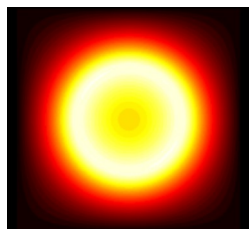
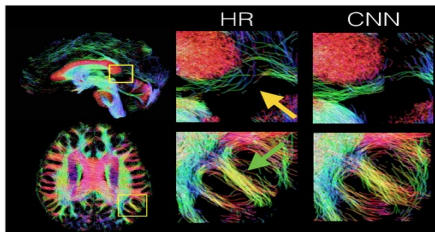
Informatics

* Prince, S. Understanding Deep Learning. MIT Press



**Machine
learning &
statistics**

**Image
processing**



**Physics-
guided
modelling**

Learners of Latents

**Aisha Shuaibu
Paula Seidler
Kieran Gibb
Ivor Simpson
Sanduni Pinnawala
Giuseppe Castiglione
Luca Trautmann
Annie Hartanto**

Life sciences



Neuroscience

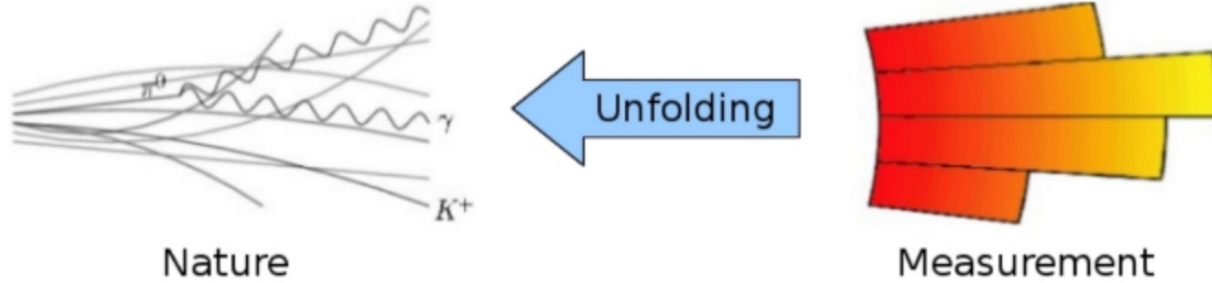
Clinical imaging sciences



**Clinical and translational
research**



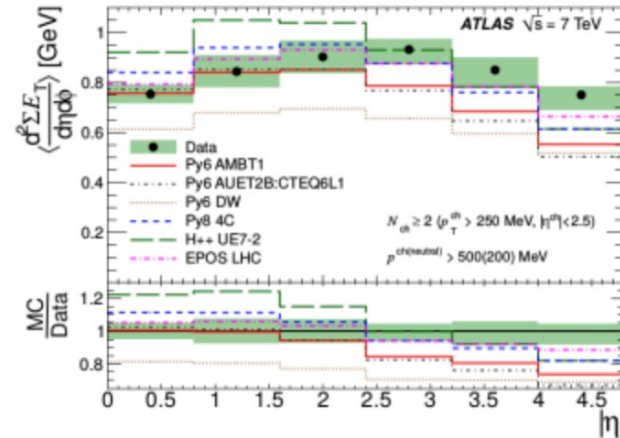
Background: PhD in particle physics



$$n(C_i^{data}) = \frac{1}{\epsilon_i} \sum_j P(T_i^{MC} | R_j^{MC}) n(R_j^{data})$$

- Real data are dependent on the detector used to measure them

Bring data back to their natural state by applying hypothesis-driven corrections derived from simulation





The Chemical Basis of Morphogenesis

A. M. Turing

Philosophical Transactions of the Royal Society of London. Series B, Biological Sciences, Vol. 237, No. 641. (Aug. 14, 1952), pp. 37-72.

Computational Modeling

$$\begin{aligned}\frac{\partial u}{\partial t} &= F(u,v) - d_u v + D_u \Delta u \\ \frac{\partial v}{\partial t} &= G(u,v) - d_v v + D_v \Delta v\end{aligned}$$

Diagram illustrating the components of the reaction-diffusion equations:

- Rate of concentration change (indicated by arrows pointing to $\frac{\partial u}{\partial t}$ and $\frac{\partial v}{\partial t}$)
- Production (indicated by an arrow pointing to $F(u,v)$)
- Degradation (indicated by an arrow pointing to $-d_u v$ and $-d_v v$)
- Diffusion (indicated by an arrow pointing to $D_u \Delta u$ and $D_v \Delta v$)
- Reaction (indicated by a bracket encompassing $F(u,v)$ and $G(u,v)$)

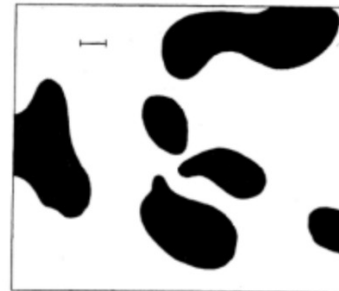
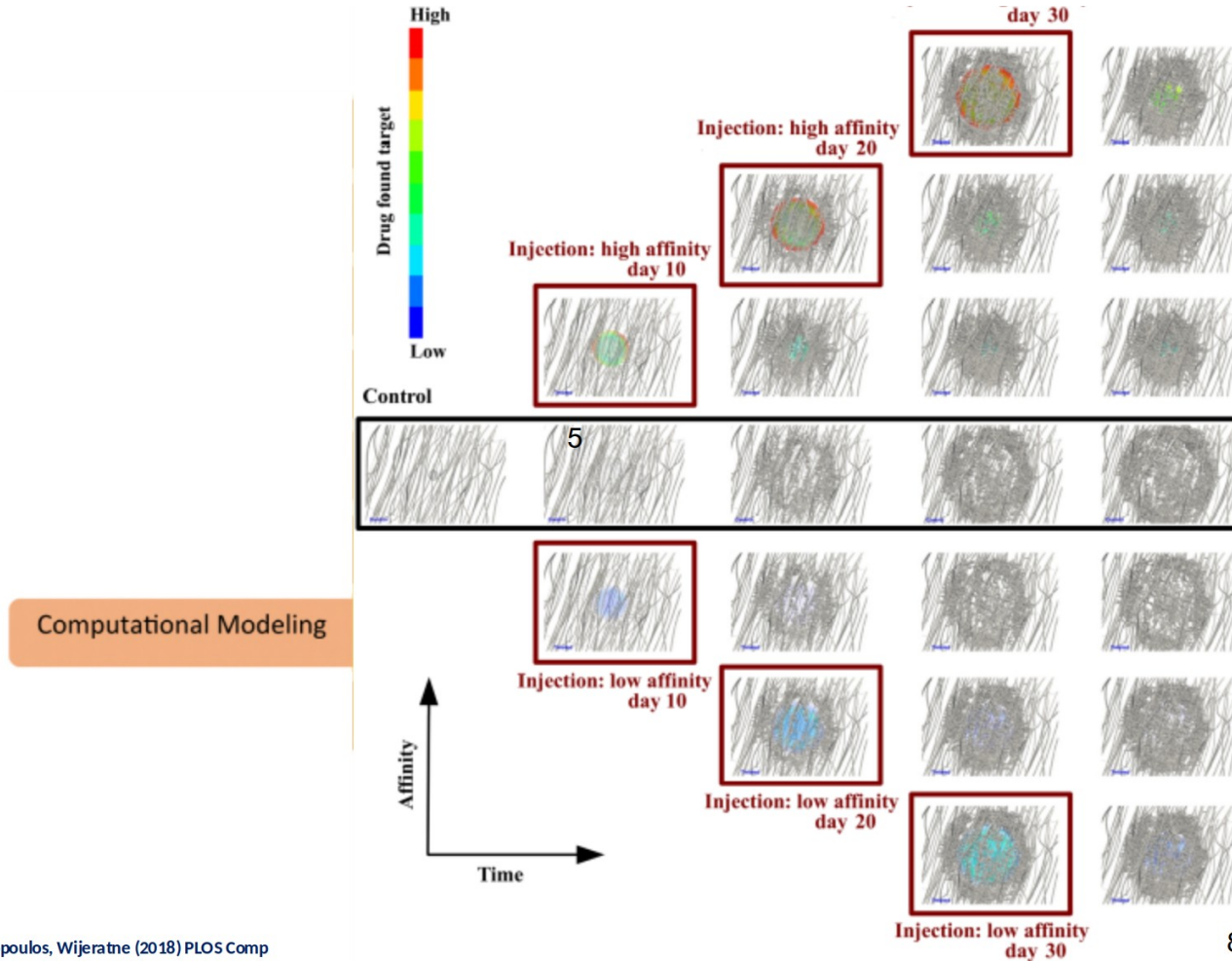


FIGURE 2. An example of a 'dappled' pattern as resulting from a type (a) morphogen system. A marker of unit length is shown. See text, §9, 11.

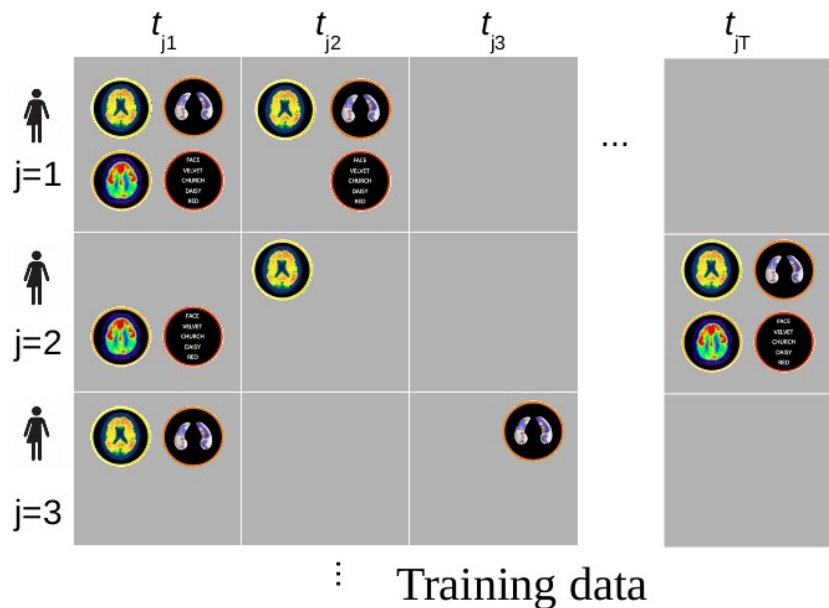
Postdoc 1: Biophysical modelling



Postdoc 2 - present: latent variable modelling of dementia

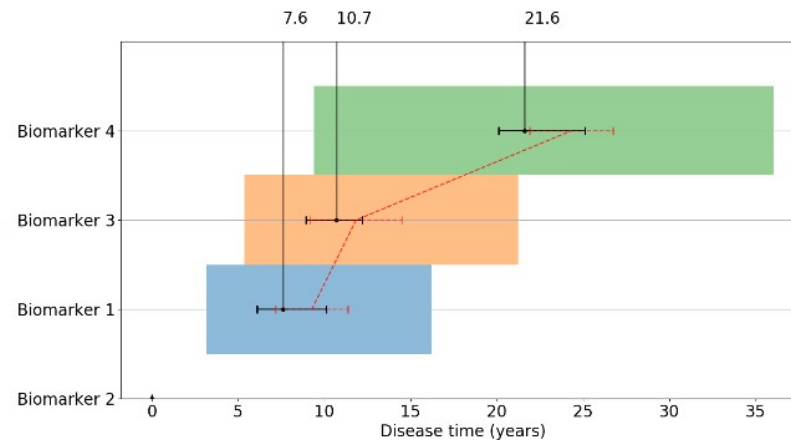
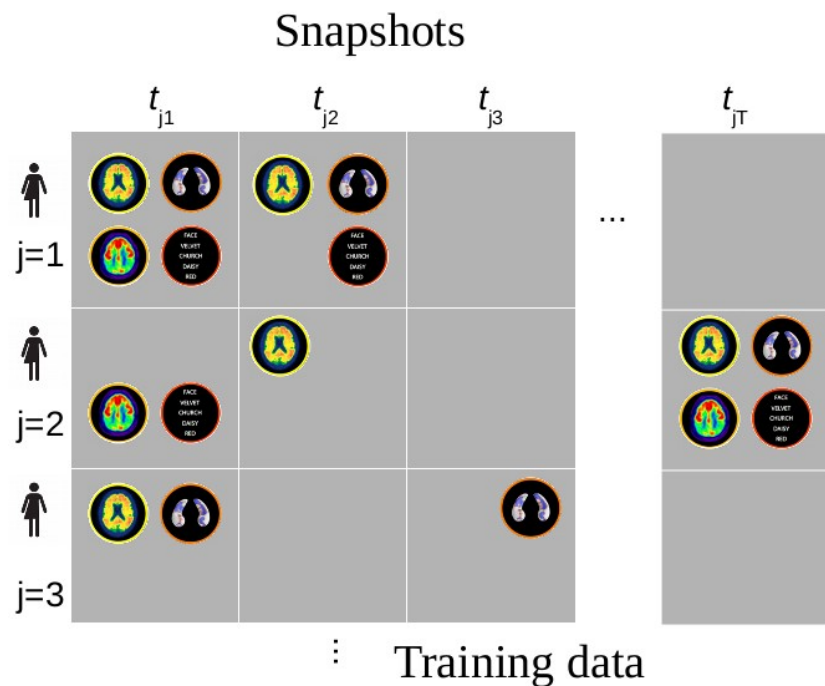
Build latent variable models (LVMs) that can leverage multi-modal data to characterise and predict progression

Snapshots



The big idea: LVM in neuro-degeneration and development

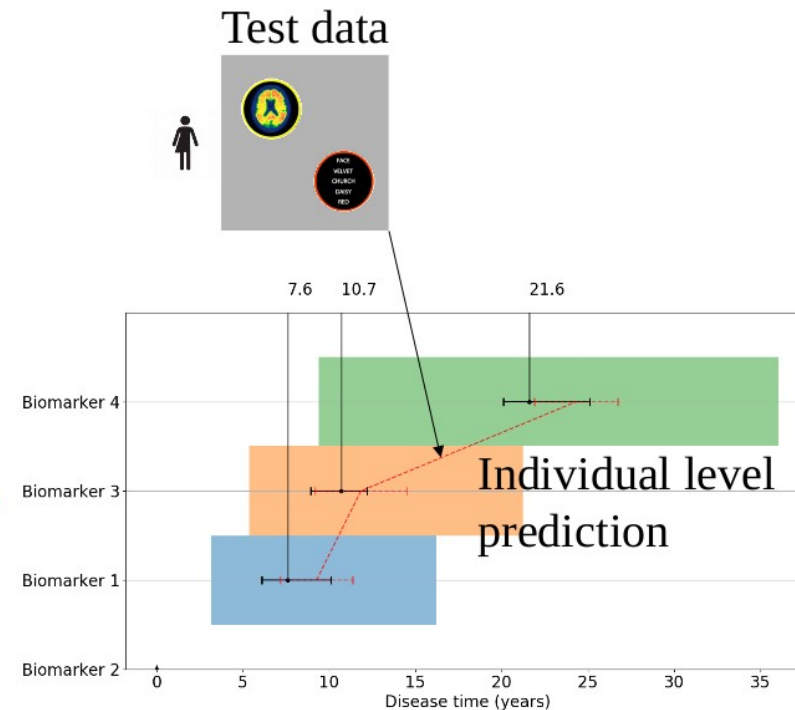
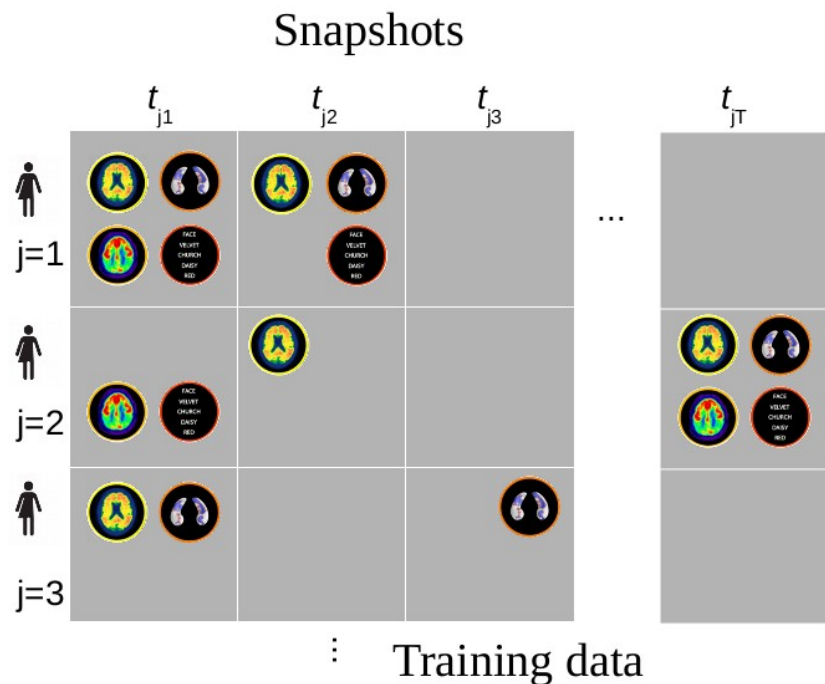
Build latent variable models (LVMs) that can leverage multi-modal data to characterise and predict progression



Group level disease timeline

The big idea: ML in neuro-degeneration and development

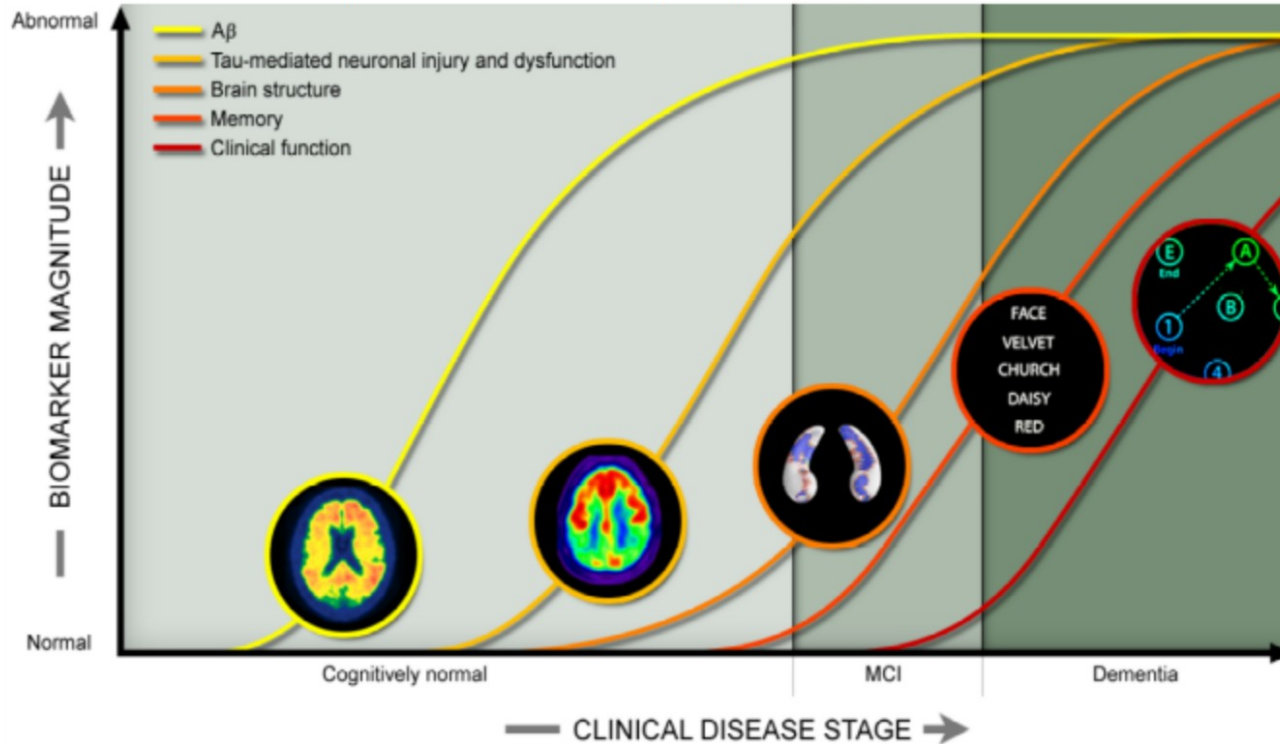
Build latent variable models (LVMs) that can leverage multi-modal data to characterise and predict progression



Group level disease timeline

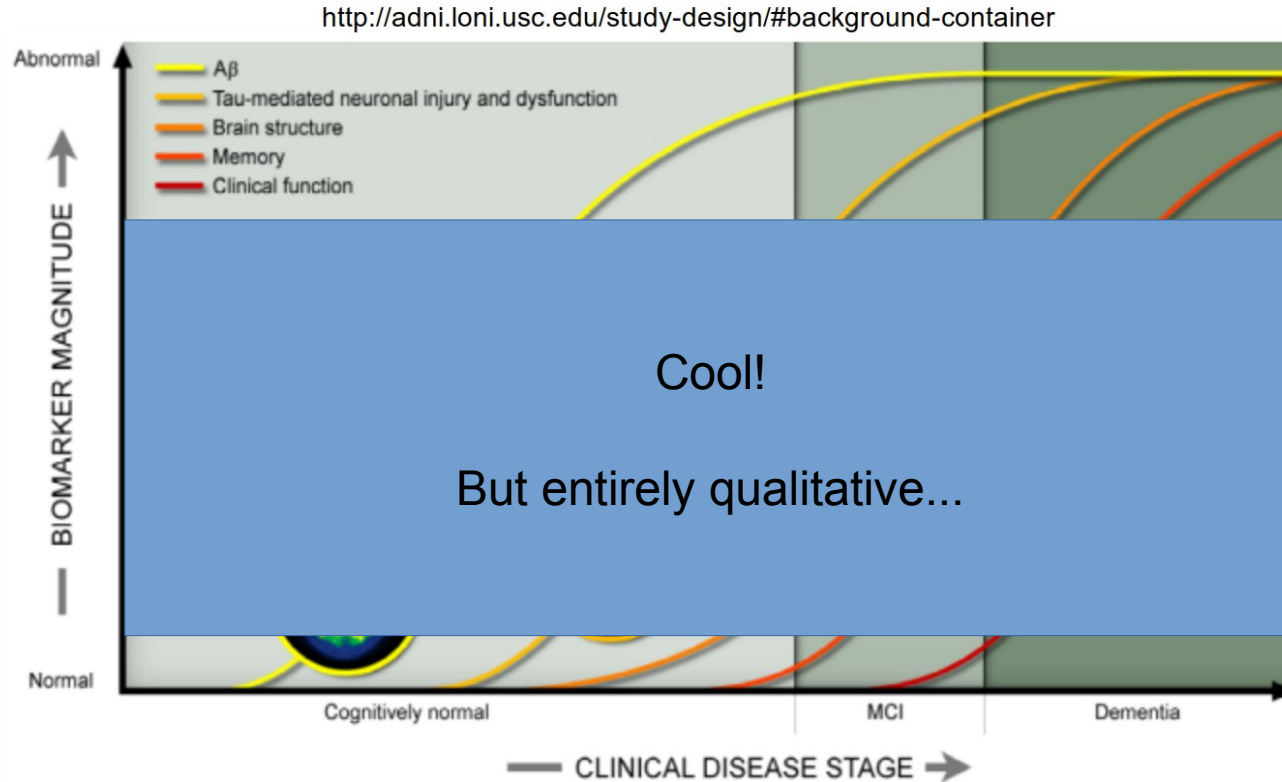
High level: disease progression modelling

<http://adni.loni.usc.edu/study-design/#background-container>



A picture of how components of a disease progresses over time

High level: disease progression modelling



A picture of how components of a disease progresses over time

Phenomenological – model disease progression in terms of observable changes in markers

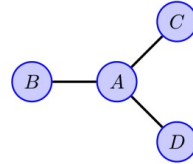
e.g., how does the brain change over the course of Alzheimer's?

Mechanistic – model disease progression in terms of underlying mechanisms

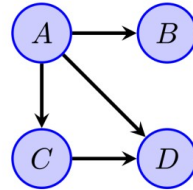
e.g., why does the brain change over the course of Alzheimer's?

Low level: disease progression modelling

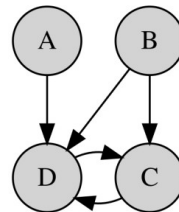
- Undirected graphical models (a.k.a. Markov networks)



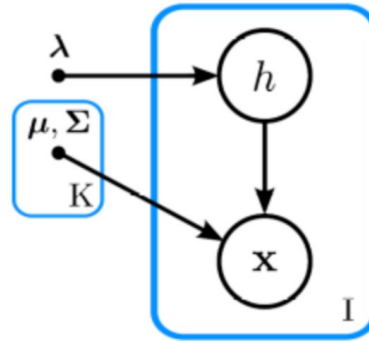
- Directed graphical models (a.k.a. Bayesian networks)
 - Directed acyclic graph (DAG)



- Directed cyclic graph



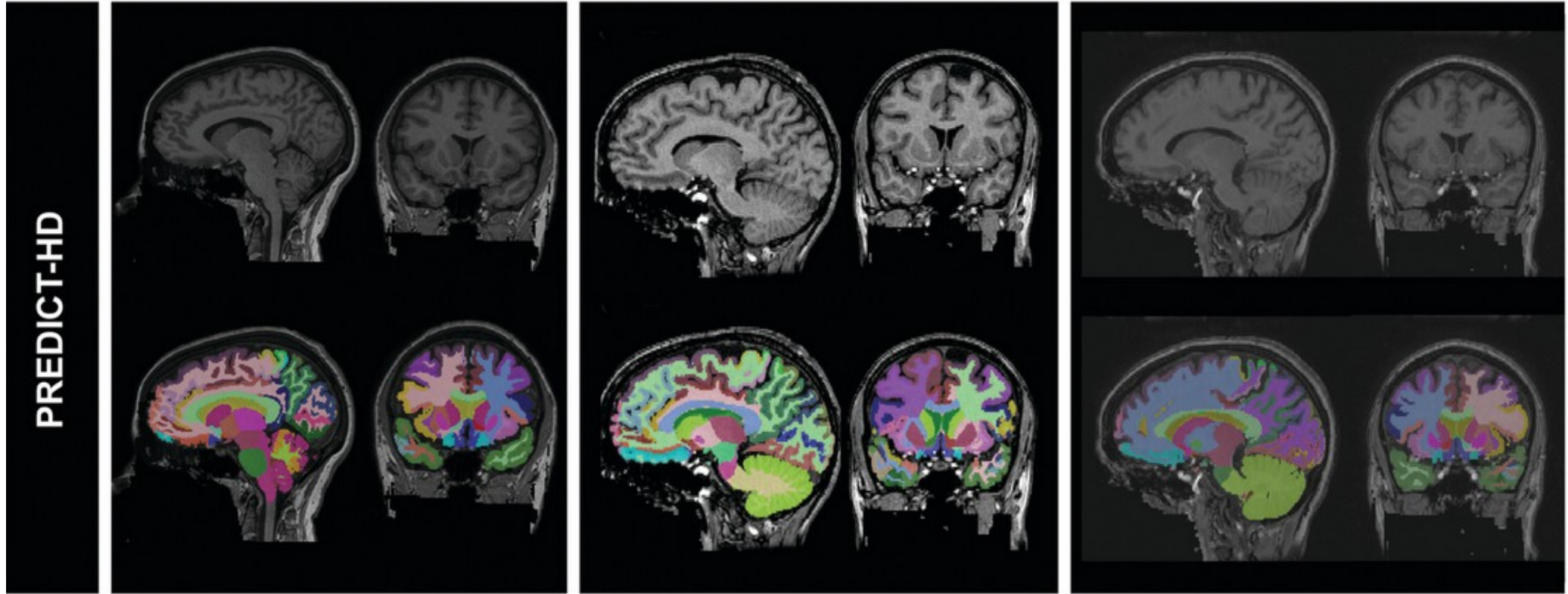
Low level: disease progression modelling



Mixture of
Gaussians

- Circles: random variables.
- Blue boxes: “plates”, signifies that the contents of the box should be repeated number of times in bottom corner.
- Bullet: variables that are not treated as uncertain.

Data: neuroimaging in humans



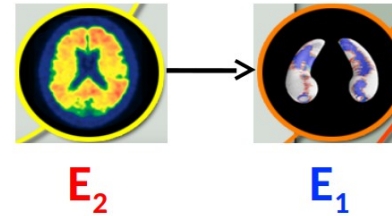
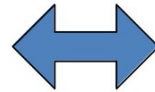
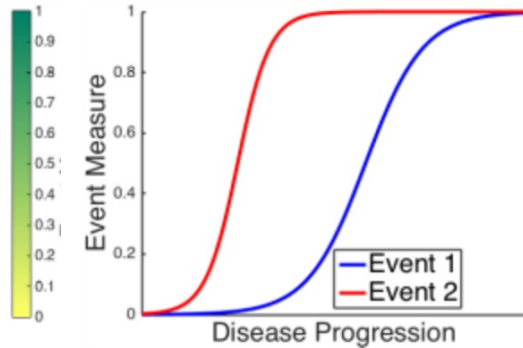
Typically use magnetic resonance imaging (MRI) data of various types as inputs to models

Classic example: the Event-Based Model (EBM)

EBM describes disease progression as a sequence of abnormality **events**

Events represent the change of a biomarker from a healthy to abnormal state

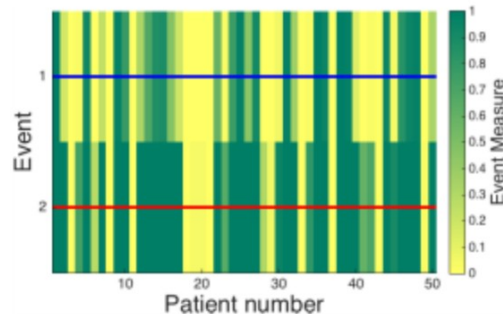
Learns from cross-sectional data of any type (imaging, clinical, biofluid...)



Simple example: 2 event measures

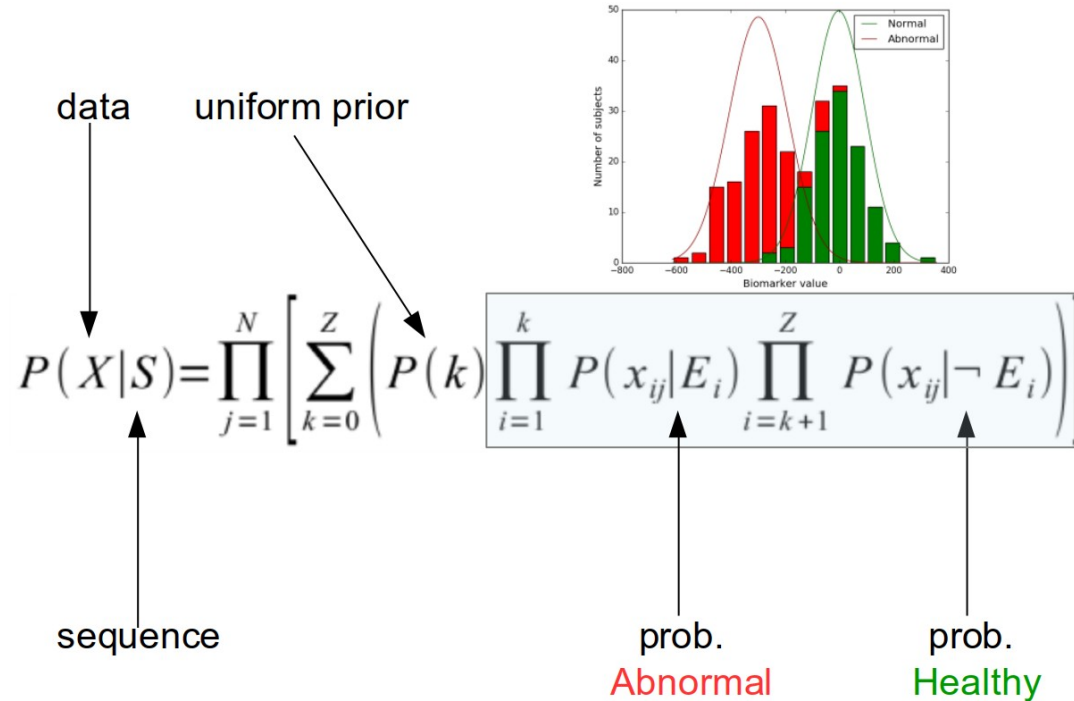
More patients have greater abnormality in Event 2 than Event 1

→ Event 2 **measurably abnormal** before Event 1



Classic example: the Event-Based Model (EBM)

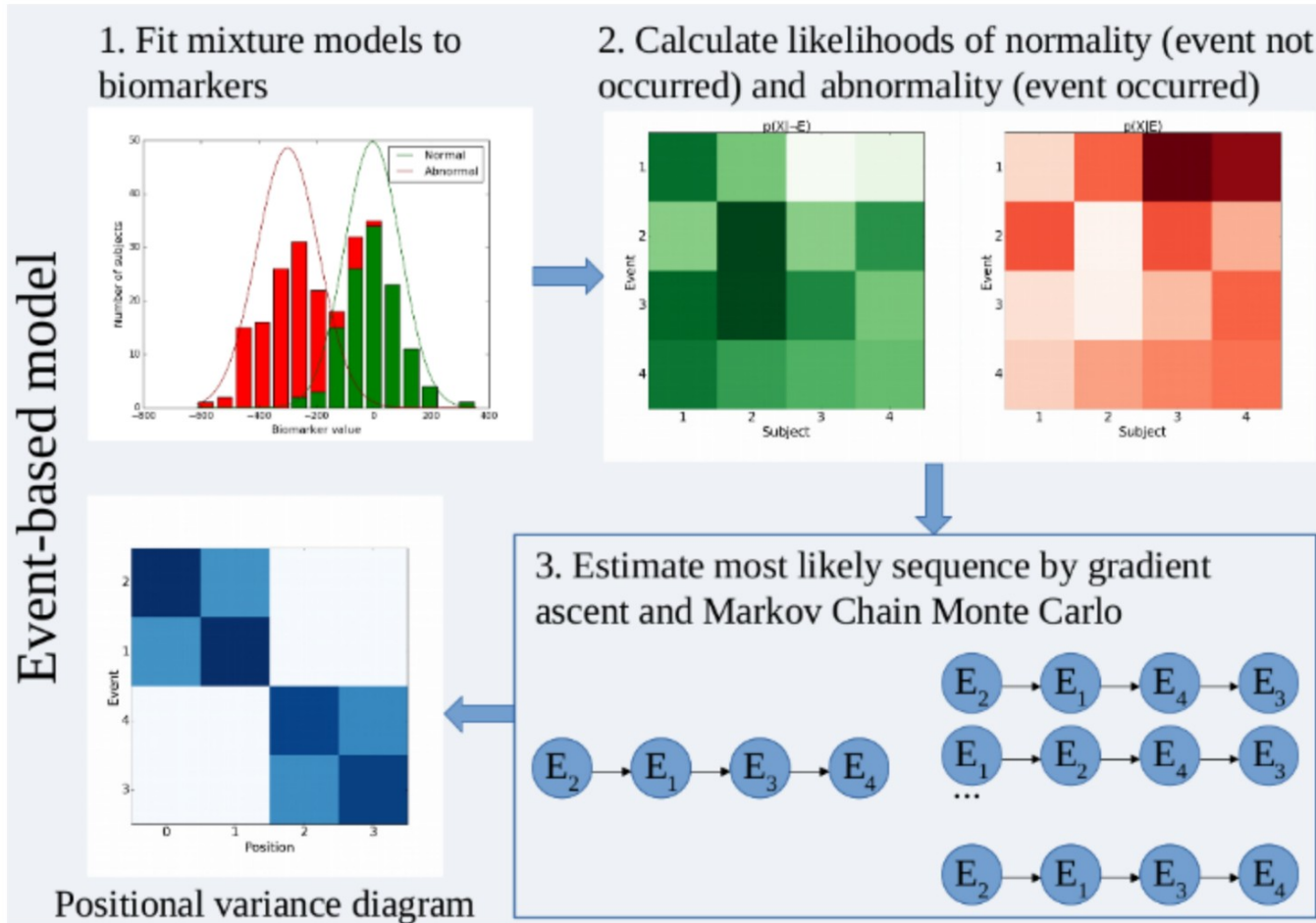
More formally: EBM is a generative model of observed data from a hidden sequence



- The EBM needs likelihood distributions for healthy and abnormal individuals

→ Learn directly from data

Classic example: the Event-Based Model (EBM)

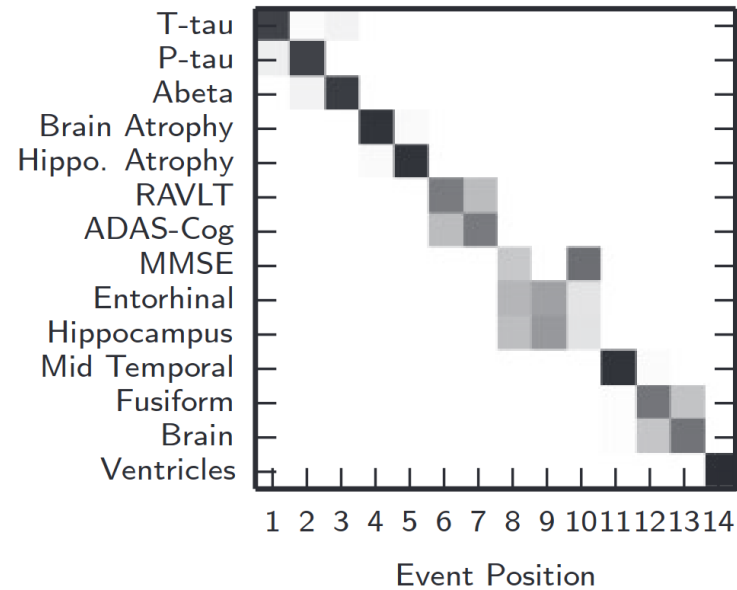


Classic example: the Event-Based Model (EBM)

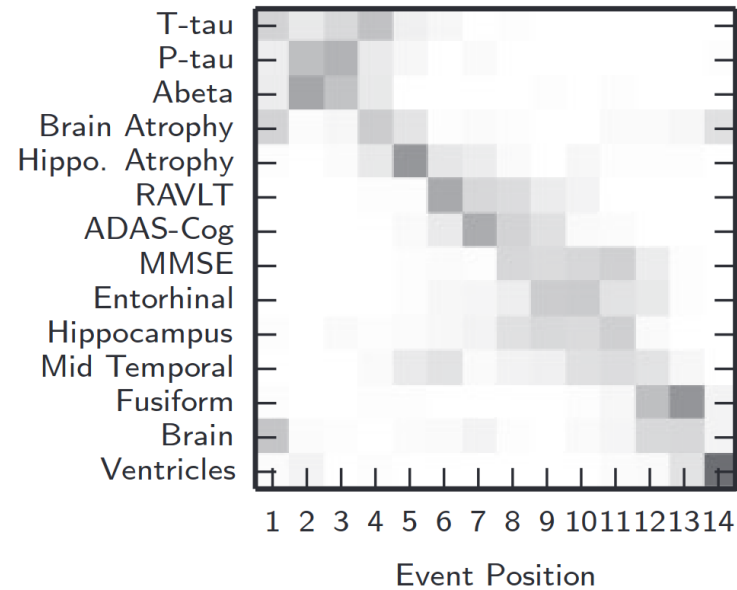
Brain 2014; 137; 2564–2577

A. L. Young et al

A Whole population



E Whole population

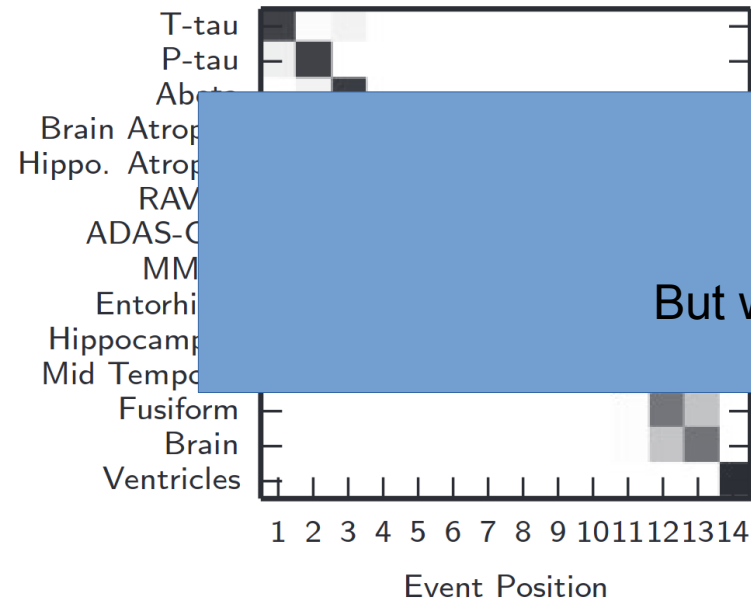


Classic example: the Event-Based Model (EBM)

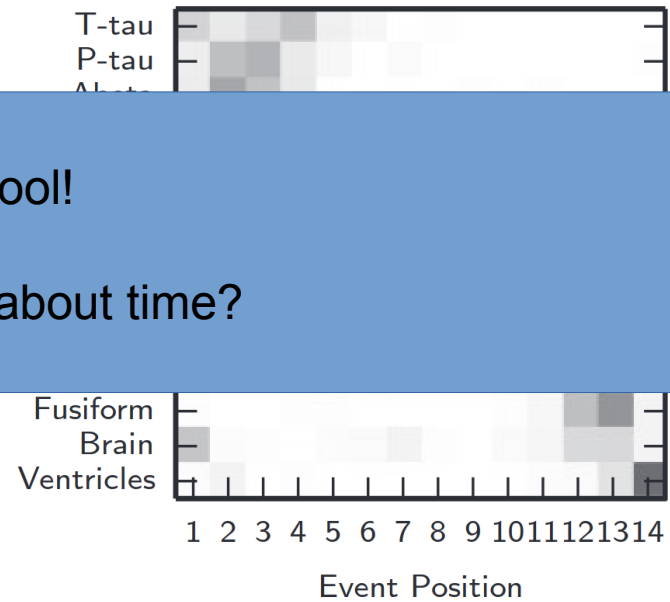
Brain 2014; 137; 2564–2577

A. L. Young et al.

A Whole population



E Whole population



Cool!

But what about time?

Continuous time hidden Markov model (CTHMM)

What's a Continuous Time Hidden Markov Model (CTHMM)?

Markov Model: a stochastic description of a sequence of observable events, where the probability of each event depends only on the previous state (ie. the probability is *conditional* on the previous state; cf. Poisson process)



Andrey Andreyevich Markov (14th June 1856 – 20th July 1922)

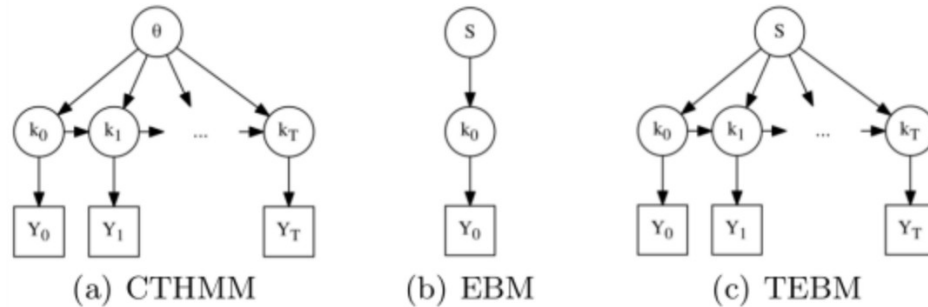
Continuous time hidden Markov model (CTHMM)

CTHMMs can be used to estimate state durations

Problem with Event-Based Model (EBM) – no time between events

Realised EBM is essentially a state-space model

→ Reformulate EBM as a special CTHMM: Temporal EBM (TEBM)



$$P(Y|\theta, S) = \prod_{j=1}^J \left[\sum_{k=0}^N P(k_{j,t=0}) \prod_{t=1}^{T_j} P(k_{j,t} | k_{j,t-1}) \prod_{t=0}^{T_j} \prod_{i=1}^{k_{j,t}} P(Y_{i,j,t} | k_{j,t}, \theta_i^p, S) \prod_{i=k_{j,t}+1}^I P(Y_{i,j,t} | k_{j,t}, \theta_i^c, S) \right]$$

Temporal Event-Based Model: provenance

- Guided by this 2014 paper on a continuous-time hidden Markov disease progression model

Unsupervised Learning of Disease Progression Models

Xiang Wang
IBM Research
Yorktown Heights, NY
wangxi@us.ibm.com

David Sontag
New York University
New York, NY
dsontag@cs.nyu.edu

Fei Wang
IBM Research
Yorktown Heights, NY
fwang@us.ibm.com

- Found this 2007 paper deriving a variable-interval continuous-time hidden Markov model

Generator Estimation of Markov Jump Processes based on incomplete observations non-equidistant in time*

Philipp Metzner, Illia Horenko, Christof Schütte
*Institute of Mathematics II, Free University Berlin,
Arnimallee 2-6, D-14195 Berlin, Germany*

- Complemented by various algorithmic implementations in this 2016 paper

Efficient Learning of Continuous-Time Hidden Markov Models for Disease Progression

[Yu-Ying Liu](#), [Shuang Li](#), [Fuxin Li](#), [Le Song](#), and [James M. Rehg](#)

- Can calculate $Q(t)$ using eigendecomposition (fast, requires Q diagonalisable) or directly using Padé method for matrix exponential (slow)

Example: the Temporal Event-Based Model (TEBM)

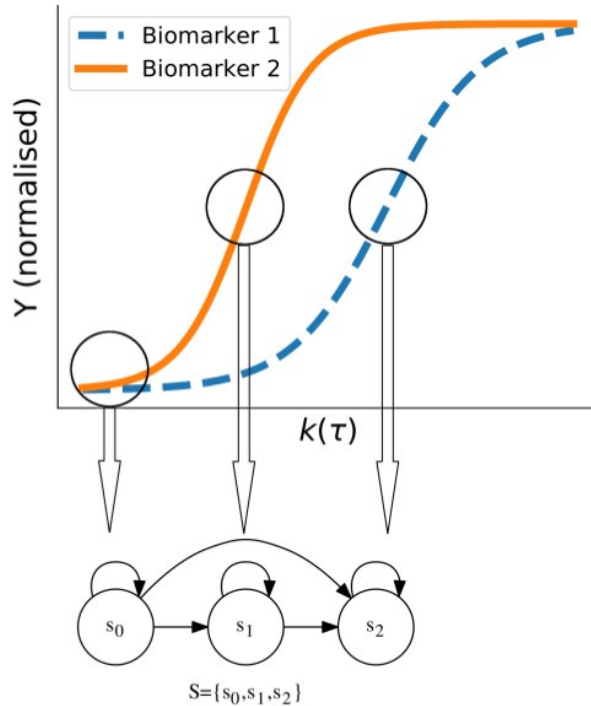
The TEBM is a generative model of observations (e.g., biomarkers) conditional on latent variables (e.g., disease states)

(2021). To formulate the TEBM, we make three main assumptions: *i*) monotonic biomarker dynamics at the group level; *ii*) a consistent event sequence across the whole population; and *iii*) Markov stage transitions at the individual level. We can write the TEBM joint distribution as a hierarchical Bayesian model using the chain rule:

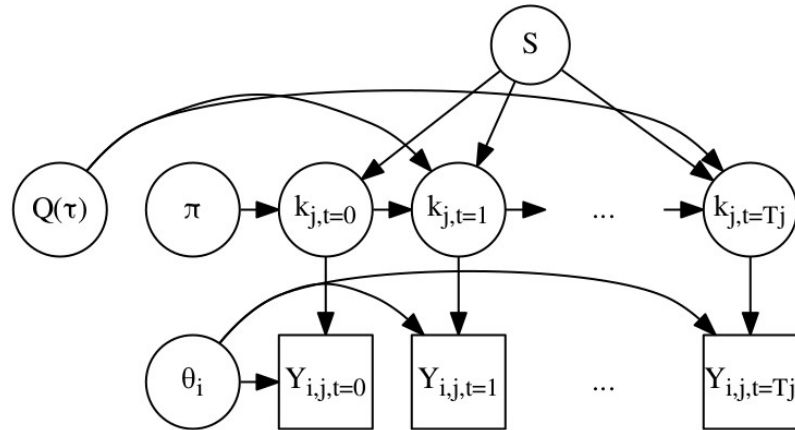
$$\begin{aligned}
 P(S, \Theta_i, k_{j,t}, Y_{i,j,t}) &= P(S, \Theta_i) \cdot P(Y_{i,j,t}, k_{j,t} | \Theta_i, S) \\
 &= P(S) \cdot P(\Theta_i) \cdot P(k_{j,t} | S, \pi, Q) \cdot P(Y_{i,j,t} | k_{j,t}, \theta_i, S).
 \end{aligned} \tag{1}$$

Example: the Temporal Event-Based Model (TEBM)

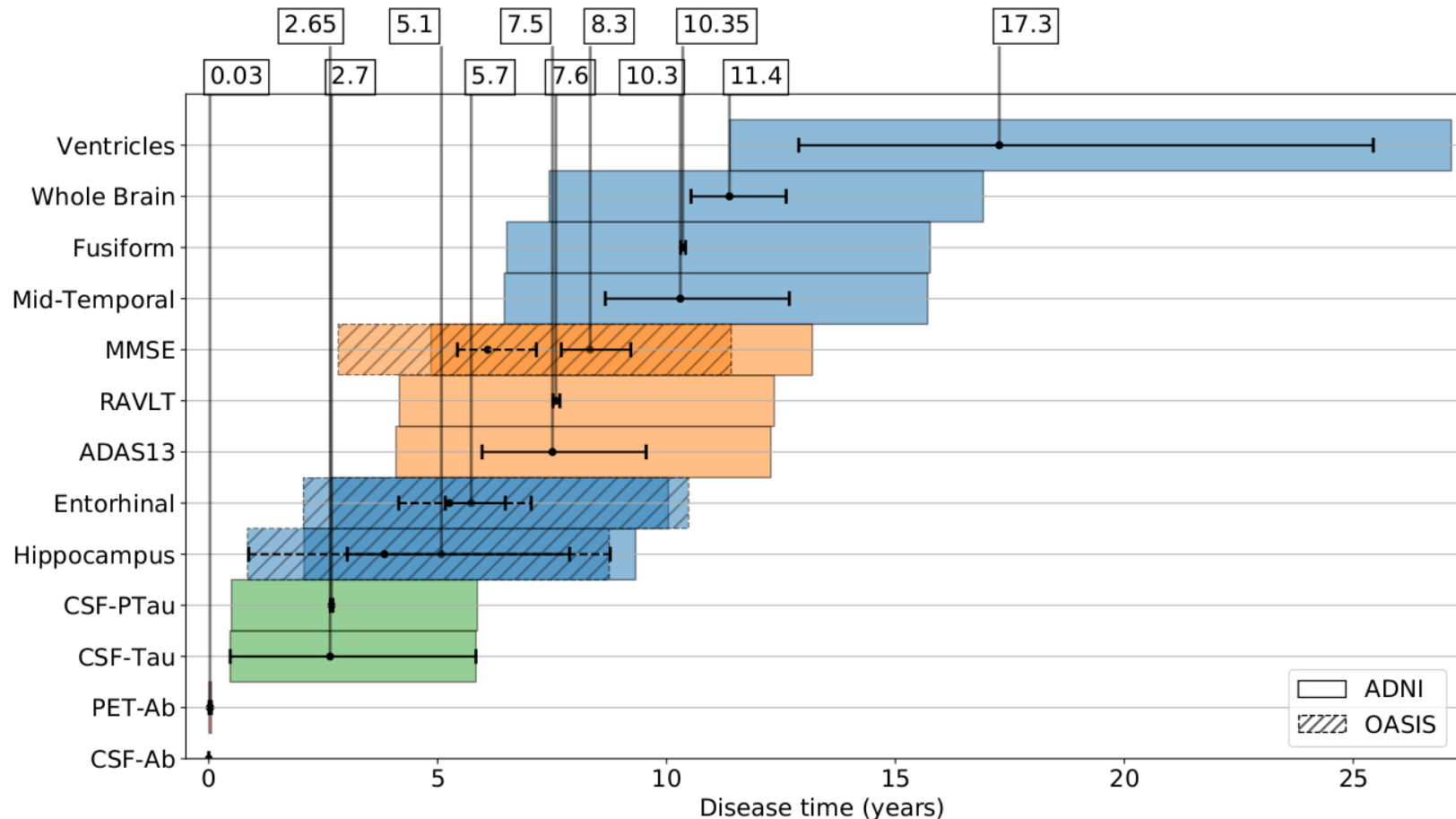
The TEBM is a generative model of observations (e.g., biomarkers) conditional on latent variables (e.g., disease states)



Graphical model

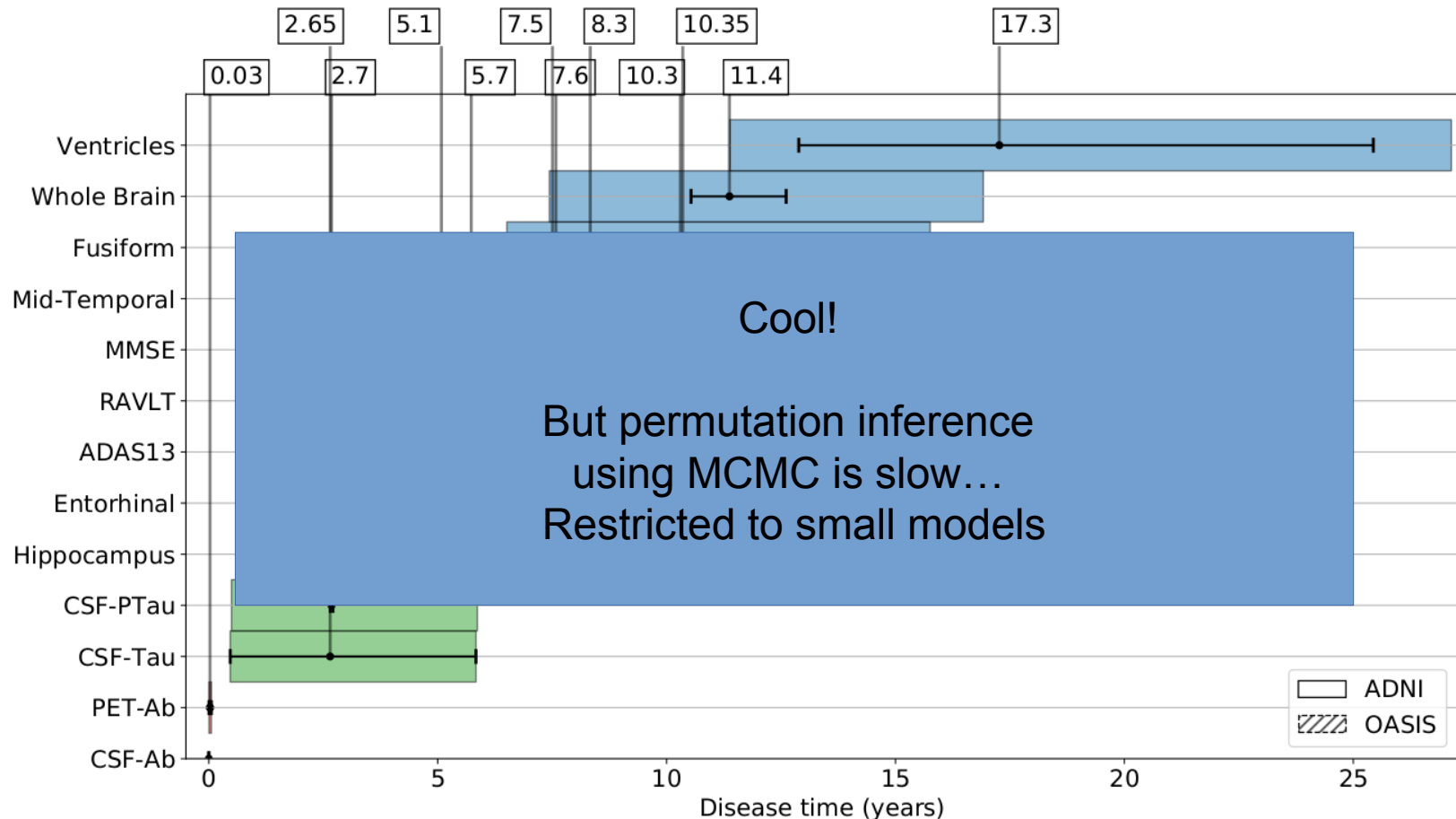


Application: learning Alzheimer's disease timeline



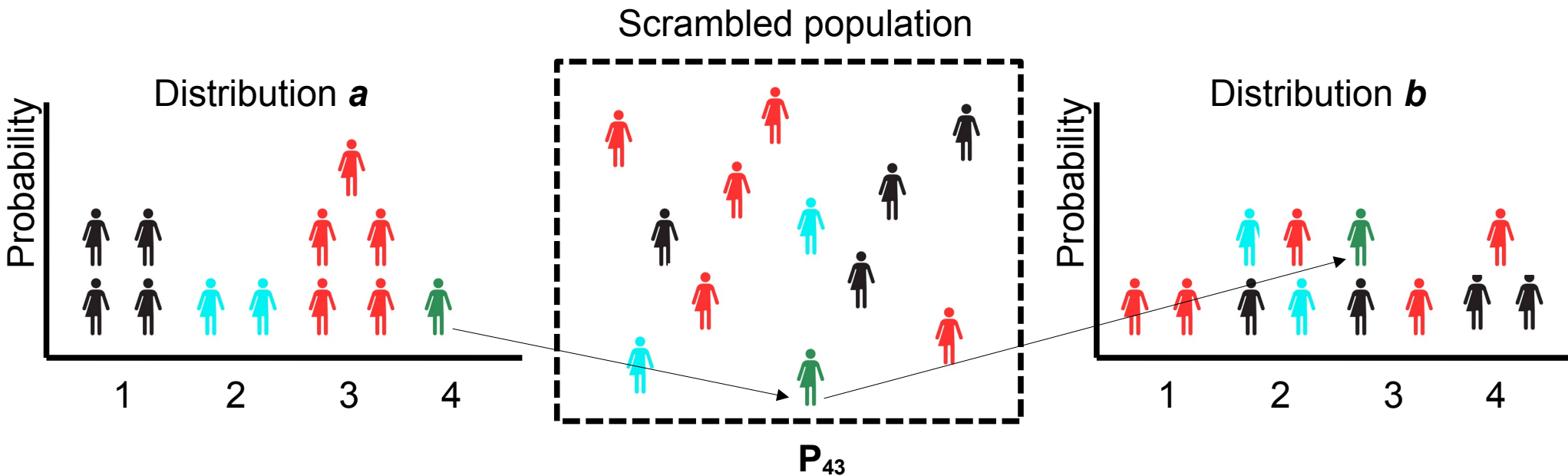
First timeline of biomarker events in Alzheimer's disease

Application: learning Alzheimer's disease timeline



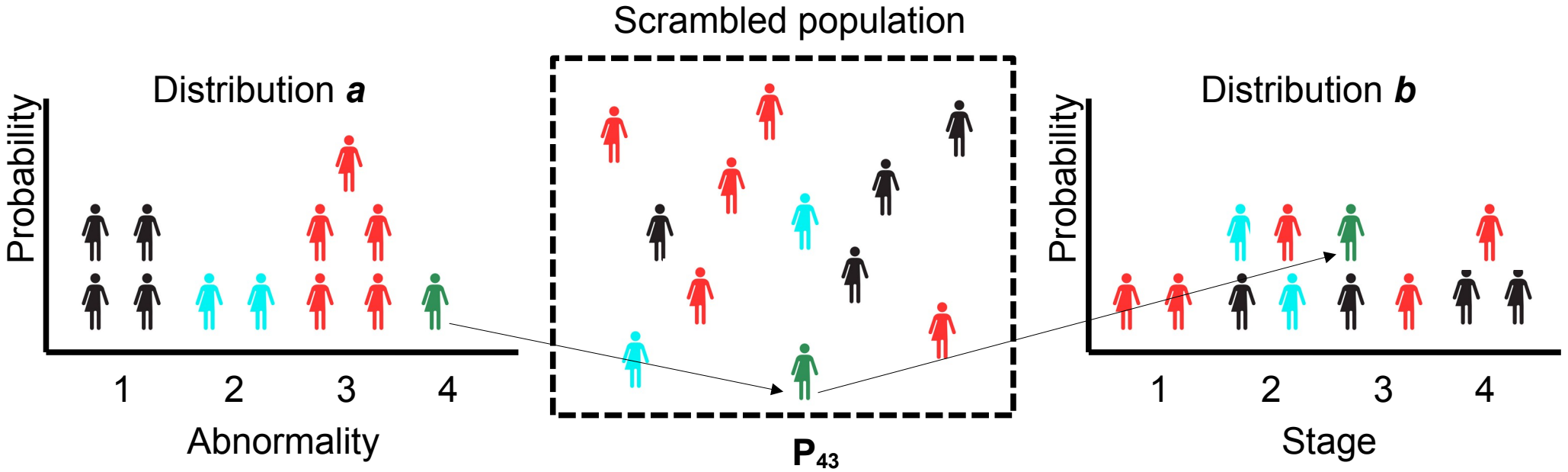
First timeline of biomarker events in Alzheimer's disease

Optimal transport



Find the optimal mapping P that minimises the cost of transporting probability distribution a to b

Idea: optimal transport for disease trajectory modelling



Transport people to their optimal (latent) stage along an event-based disease trajectory

Variational event-based model: key idea

$$\mathcal{B}_N = \left\{ X : \begin{array}{l} X_{m,n} \geq 0 \quad \forall m, n \in 1, \dots, N; \\ \sum_{n=1}^N X_{m,n} = 1 \quad \forall m \in 1, \dots, N; \\ \sum_{m=1}^N X_{m,n} = 1 \quad \forall n \in 1, \dots, N \end{array} \right\}.$$

These linear row- and column-normalization constraints restrict \mathcal{B}_N to a $(N - 1)^2$ dimensional subset of $\mathbb{R}^{N \times N}$.

Reframe the discrete sequence s as a permutation matrix S belonging to the Birkhoff polytope

Aside: Birkhoff polytopes

What's a Birkhoff polytope?

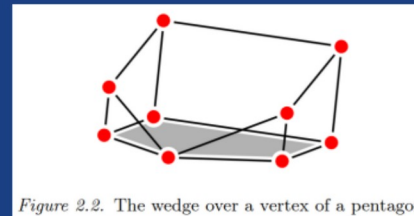
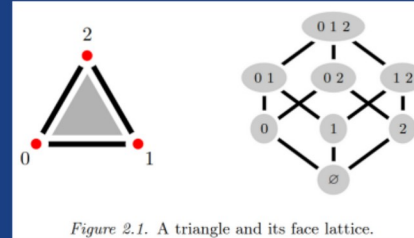
https://en.wikipedia.org/wiki/Birkhoff_polytope
Paffenholz, 2013. arXiv:1304.3948

“The Birkhoff polytope, B , is the convex polytope in \mathbb{R}^N (where $N = n^2$) whose points are the doubly stochastic matrices, X , i.e., the $n \times n$ matrices whose entries are non-negative real numbers and whose rows and columns each add up to 1.”

→ Maps permutation matrices, X , to geometric objects, B

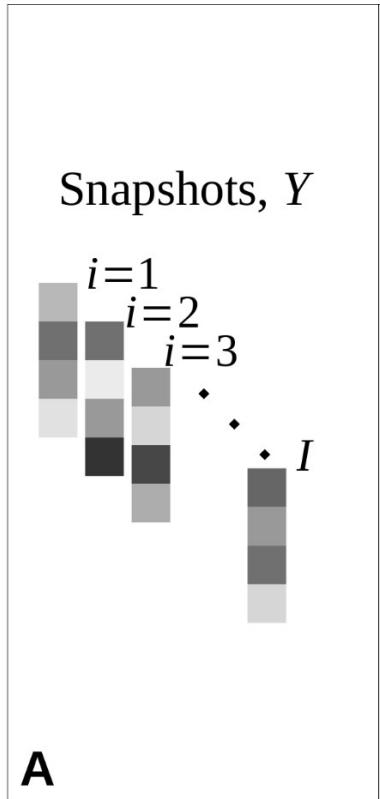
→ The top vertex in Figure 2.1 would have a permutation matrix like:

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = X$$



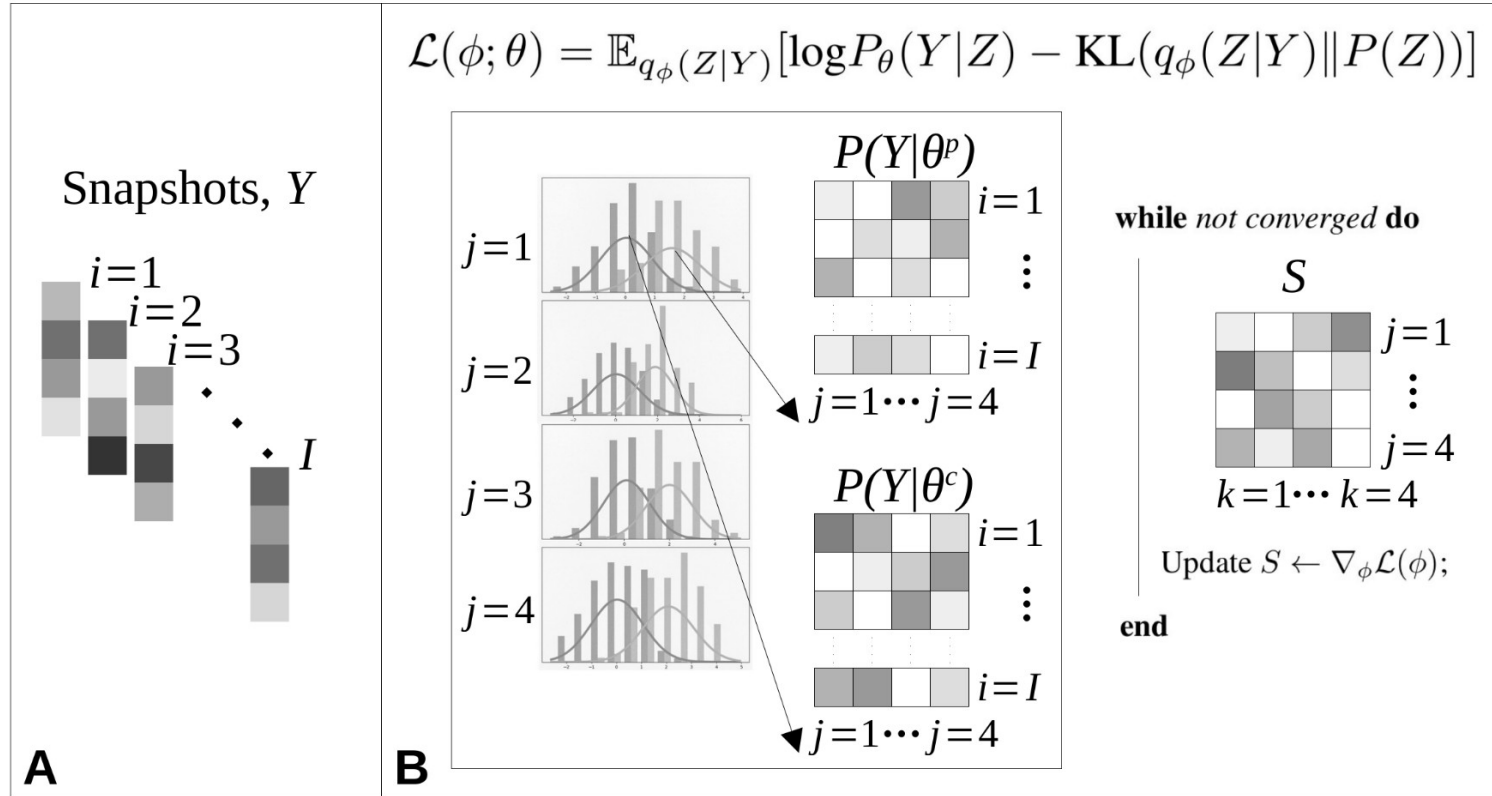
Reframe the discrete sequence s as a permutation matrix S belonging to the Birkhoff polytope

Variational event-based model



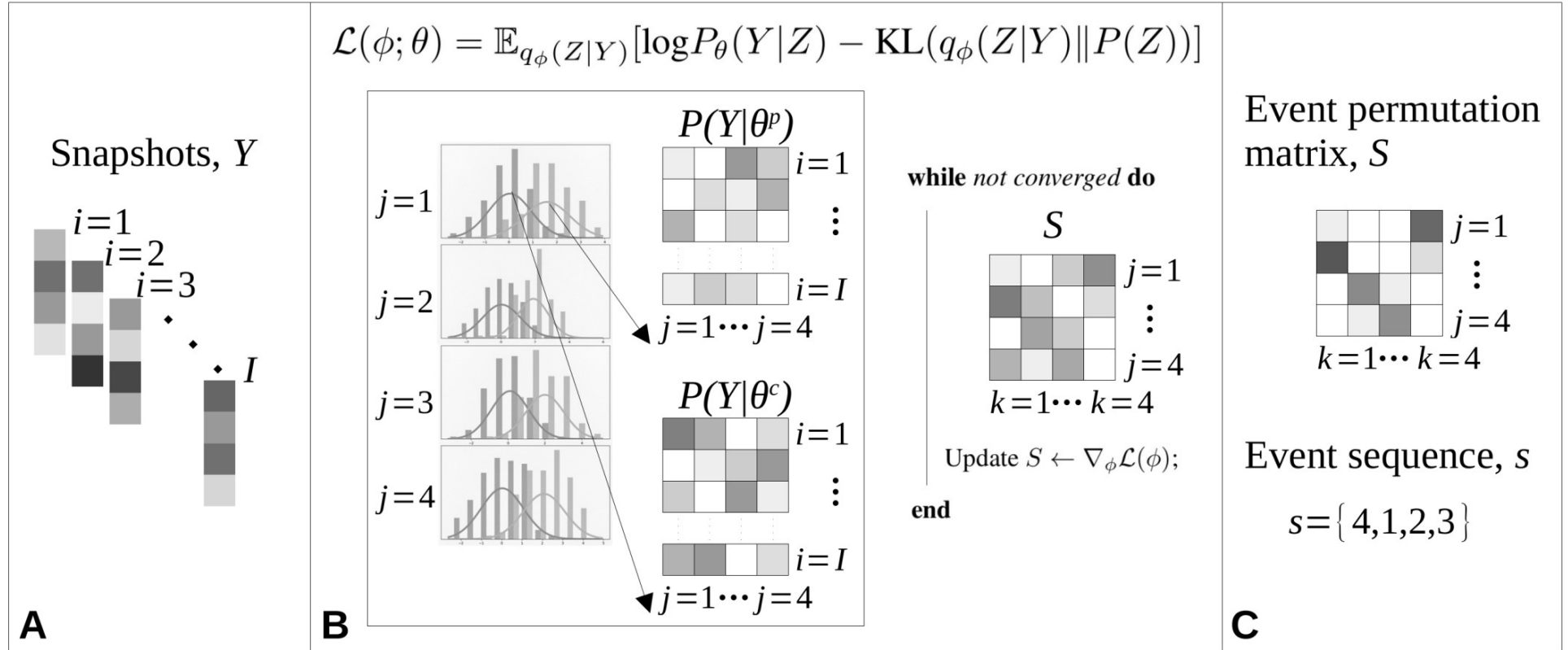
Input “snapshots” (single observations) from different individuals

Variational event-based model



Model likelihood specified by distributions “normality” and “abnormality”

Variational event-based model



Learn optimal permutation of hidden events and corresponding event sequence

Variational event-based model: key ingredients

$$K(X/\tau) = \operatorname{argmax}_{S \in \mathcal{B}_N} \langle S, X \rangle_F + \tau H(S).$$

Entropy-regularised optimal transport problem

Cuturi. NeurIPS 2013, doi: arXiv.1306.0895

$$M(X) = \begin{bmatrix} e_{s(0)} \\ \vdots \\ e_{s(N)} \end{bmatrix} = \lim_{\tau \rightarrow 0} K(X/\tau).$$

Hard permutation from Sinkhorn-Knopp operator

Sinkhorn & Knopp. Pacific Journal of Mathematics, 1967

$$G(X, \tau) \sim K((X + \epsilon)/\tau).$$

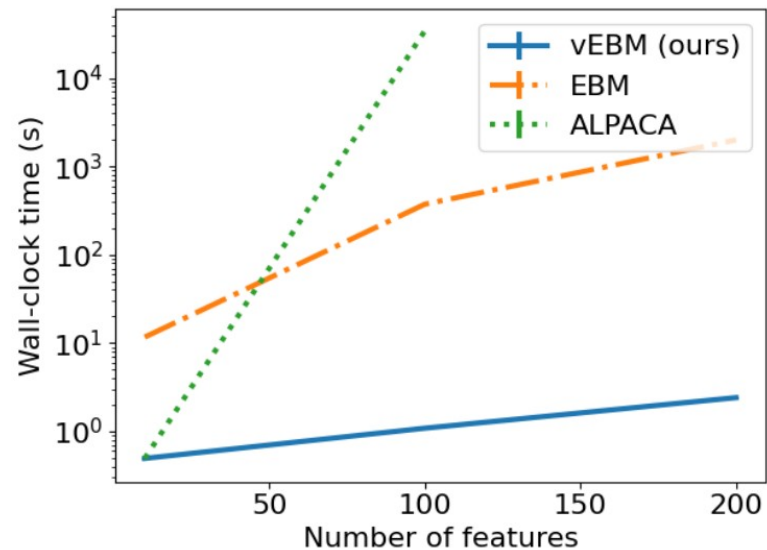
Gumbel-Sinkhorn distribution

Mena et al. ICLR 2018, doi: arXiv.1802.08665

$$\begin{aligned} \log P(Y) \geq \mathcal{L}(\phi; \theta) &= \mathbb{E}_{q_\phi(Z|Y)} [\log P_\theta(Y|Z) - \text{KL}(q_\phi(Z|Y) \| P(Z))] \\ &= \mathbb{E}_{q_\phi(Z|Y)} [\log P_\theta(Y|Z) - \text{KL}(G_\phi(X, \tau) \| G(X = 0, \tau_{\text{prior}}))]. \end{aligned}$$

Enable differentiability by parametrising prior & posterior using Gumbel-Sinkhorn distribution

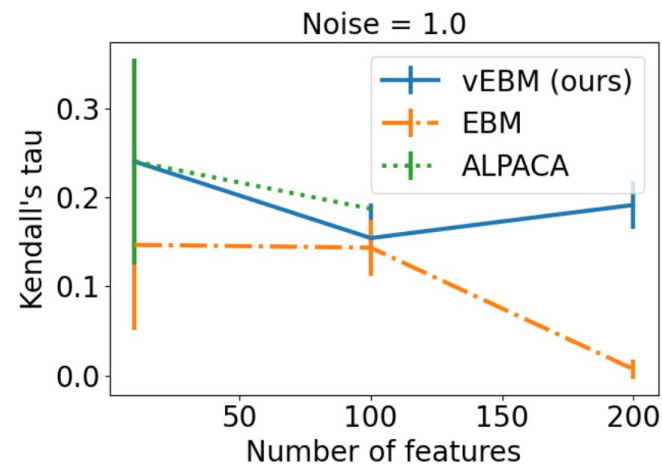
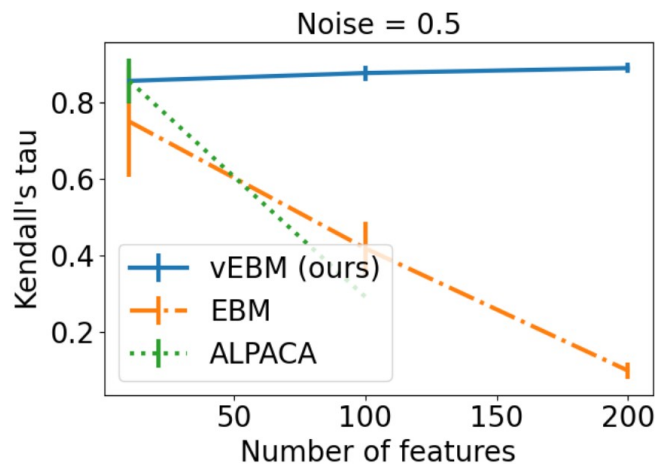
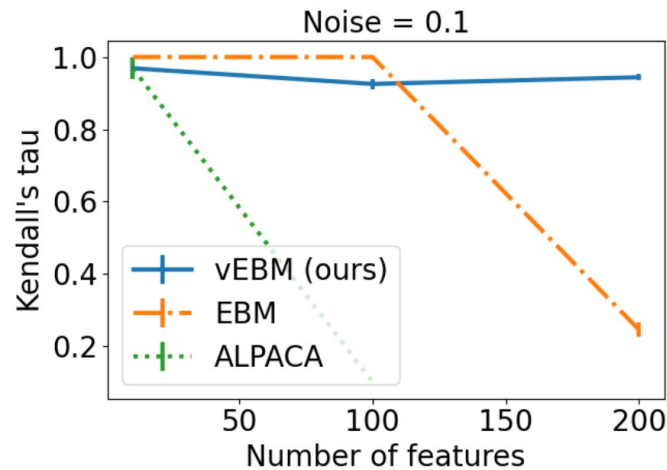
Fast inference



>1000 x faster than baselines,
which use maximum likelihood

Robust to noise

Maintains inference accuracy
with increasing noise



Real data: pixel-level atrophy using tensor-based morphometry data

Use ADNI dataset “TBM Jacobian
Maps MDT-SC”

Cross-sectional TBM maps
from 816 individuals
(299 controls,
399 mild cognitive impairment,
188 AD)

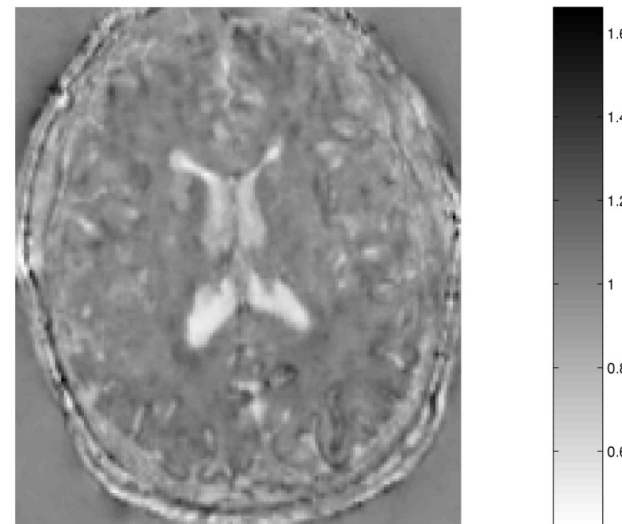


Figure 6.4: This figure illustrates the volume changes estimated by warping together the images shown in Figure 6.3. The relative volumes are the Jacobian determinants of the deformation field. Smaller determinants are obtained when a region of the template maps to a smaller region in the source image. In this example, they represent regions that have expanded between the early and late scans. Regions where there are no measurable volume changes have Jacobian determinants with a value of one.

[https://www.fil.ion.ucl.ac.uk/spm/doc/books/hbf2/pdfs/
Ch6.pdf](https://www.fil.ion.ucl.ac.uk/spm/doc/books/hbf2/pdfs/Ch6.pdf)

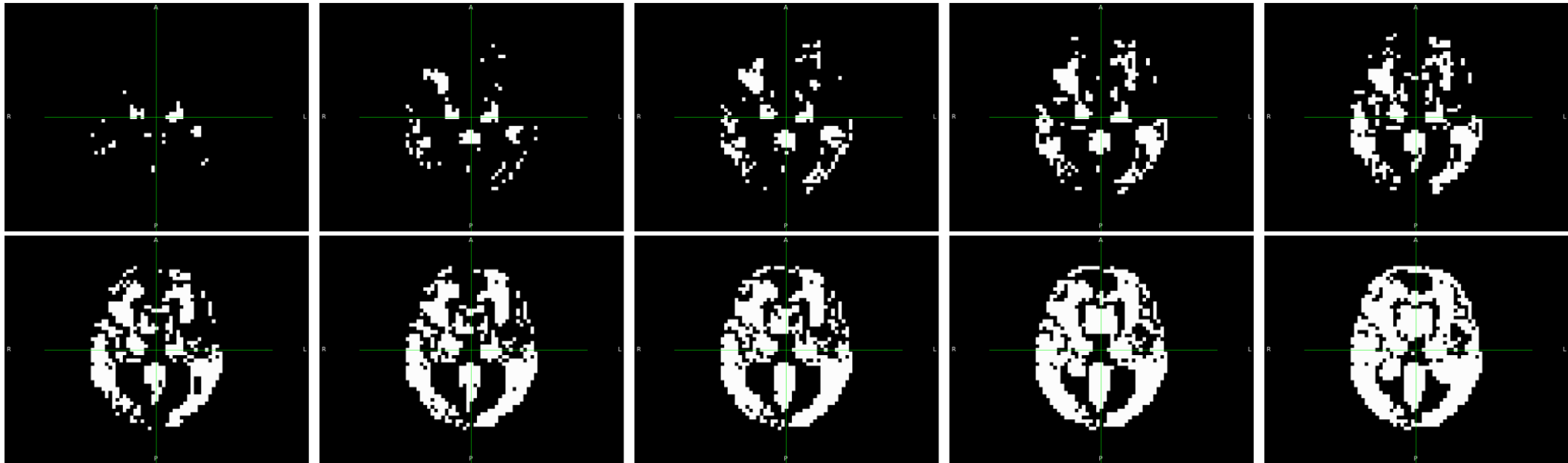
*Jacobian Map == Deformation tensor

Pixel-level progression Alzheimer's disease (AD)



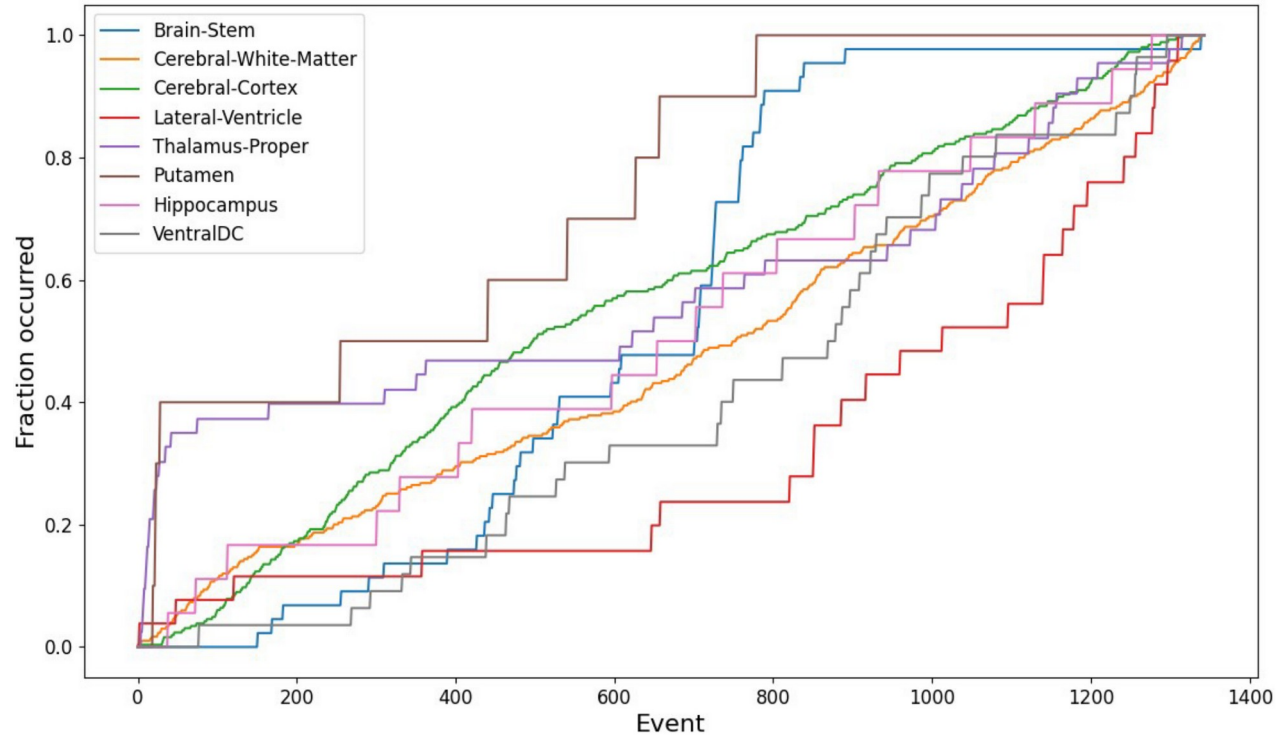
New insights into tissue-level AD progression

Pixel-level progression Alzheimer's disease (AD)



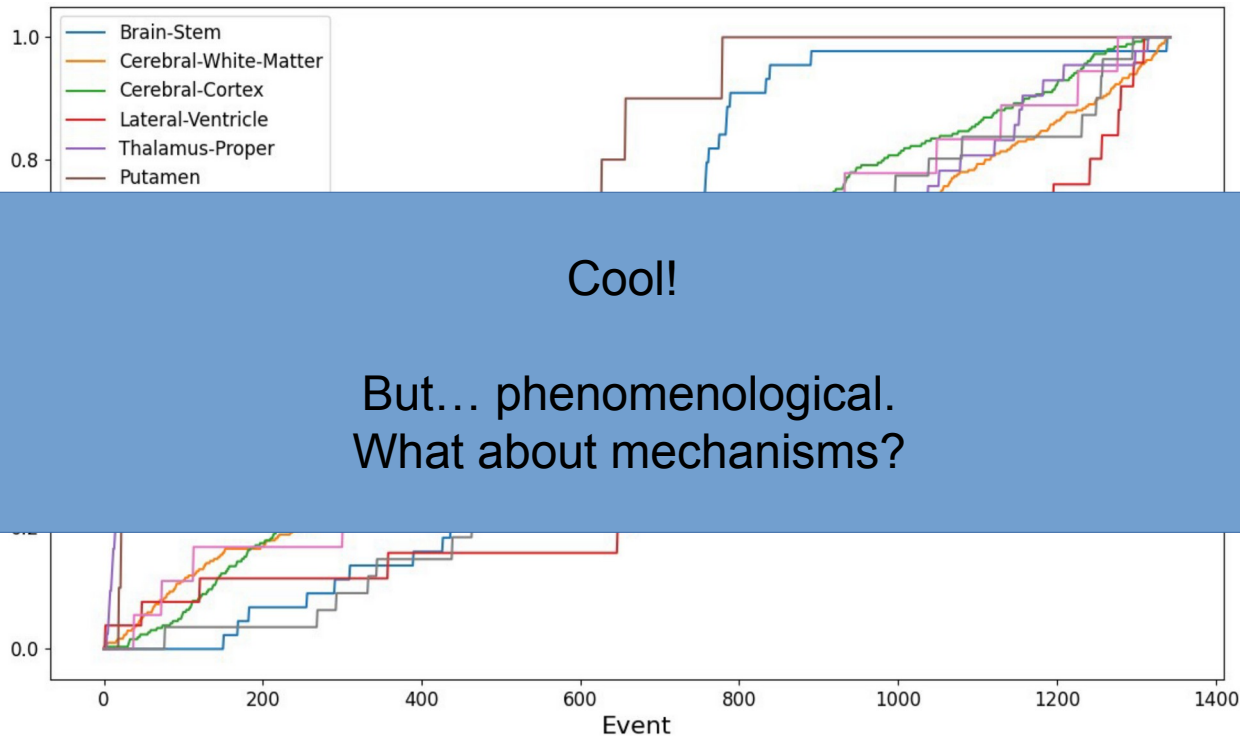
New insights into tissue-level AD progression

Pixel-level progression Alzheimer's disease (AD)



New insights into tissue-level AD progression

Pixel-level progression Alzheimer's disease (AD)



New insights into tissue-level AD progression

Mechanistic modelling of disease propagation

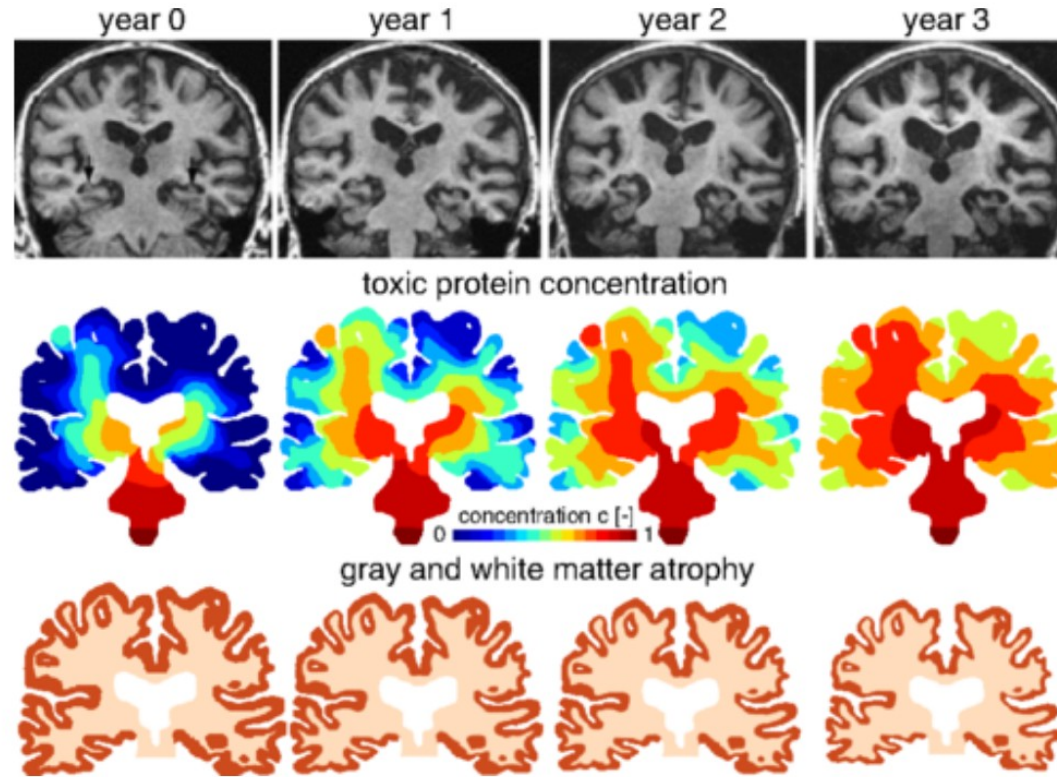


Figure 1: **Top Image:** MRI scans of an Alzheimer's patient showing yearly progression, highlighting increased hippocampal atrophy, enlarged ventricles, and widening cortical sulci. **Middle Image:** Annual increase in toxic protein concentration, starting from the brain stem. **Bottom Image:** Simulated annual atrophy patterns, correlating activation time and toxic protein concentration. [Weickenmeier, J., Kuhl, E., & Goriely, A. \(2018\). Multiphysics of prionlike diseases: Progression and atrophy. Physical review letters, 121 \(15\), 158101. \(<https://creativecommons.org/licenses/by/4.0/>\)](#)

Mechanistic modelling of disease propagation

BrainPhys

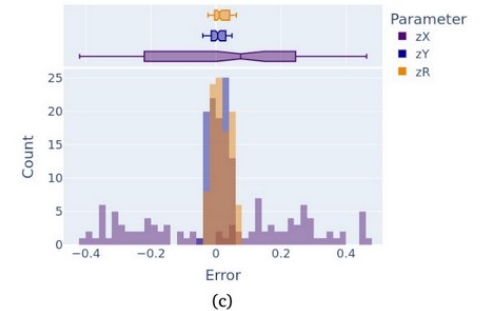
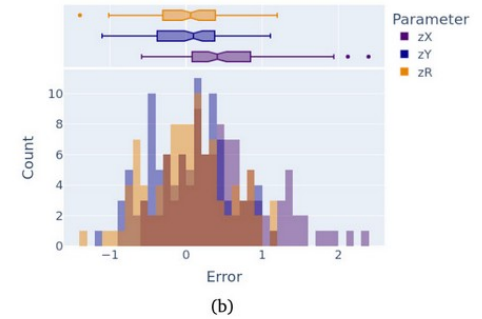
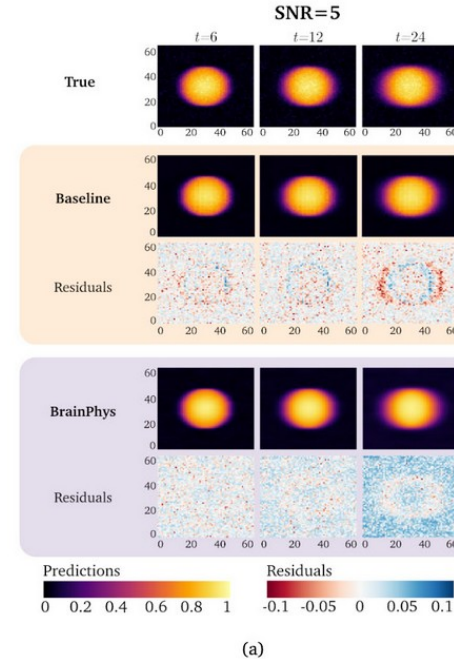
Challenges in studying mechanisms of neurodegeneration

- Incomplete knowledge of disease biology
- Scarcity of longitudinal imaging data

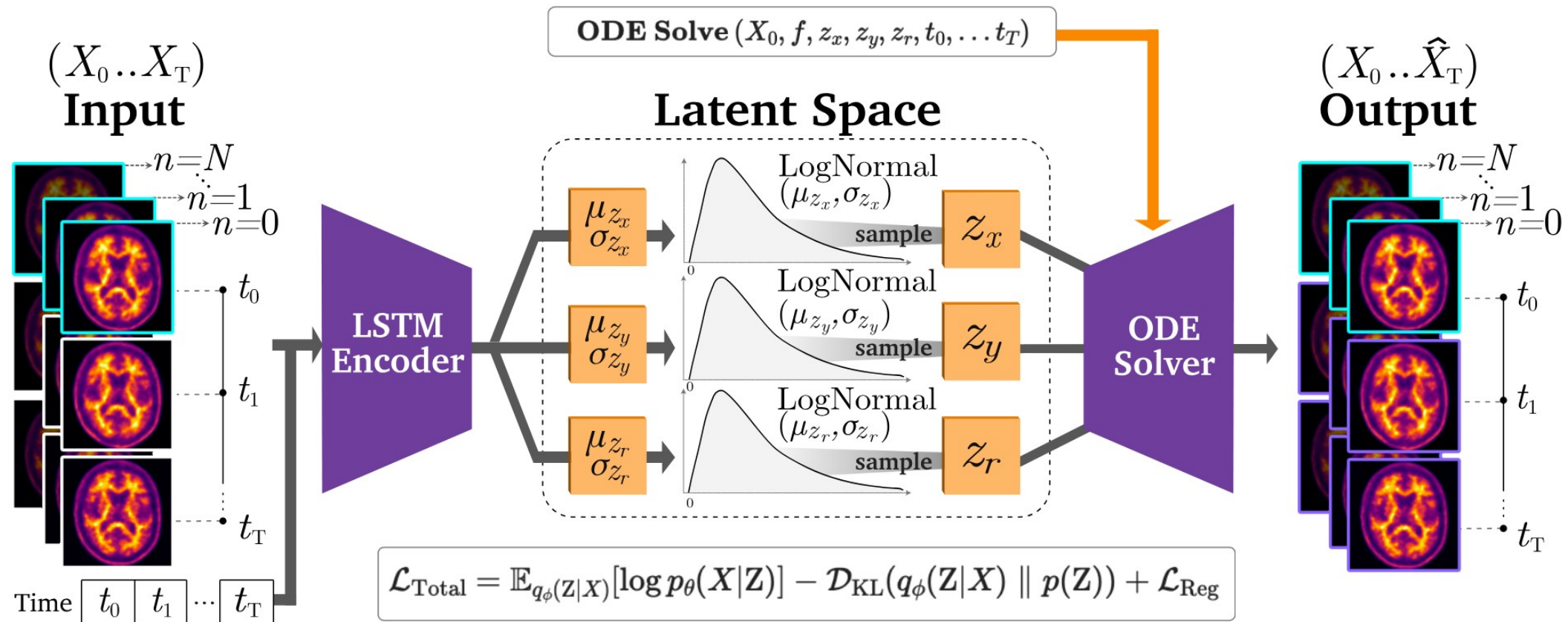
Limitations of conventional deep learning

- Lack interpretability (act as black boxes)
- Demand large datasets

Physics informed machine learning combines data-driven methods with physical constraints to **improve interpretability**



Mechanistic modelling of disease propagation



Mechanistic modelling of disease propagation

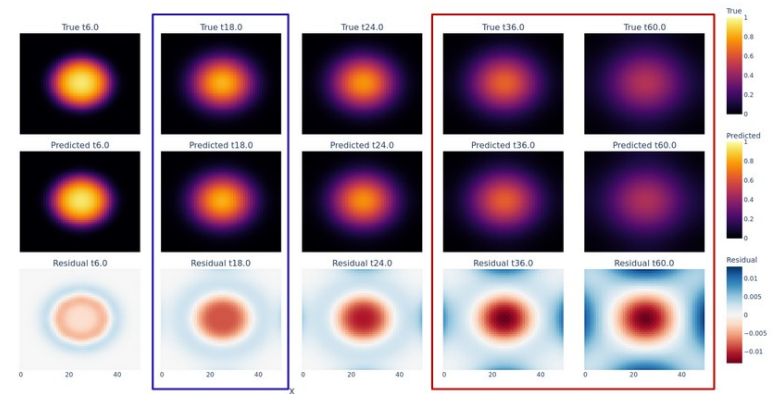
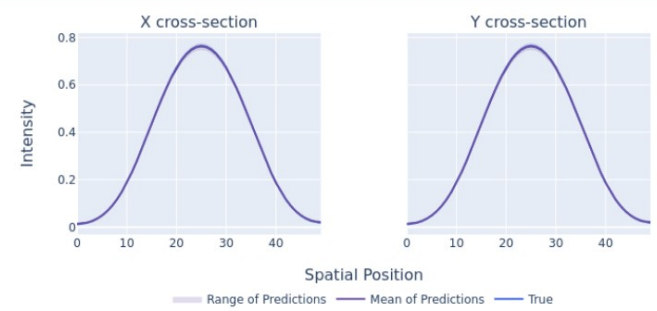
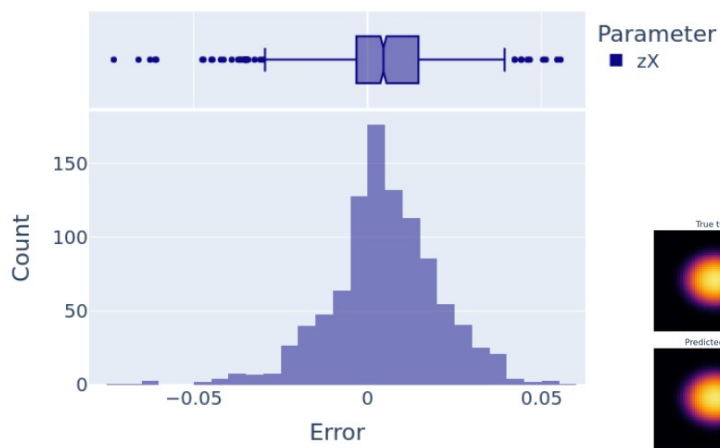
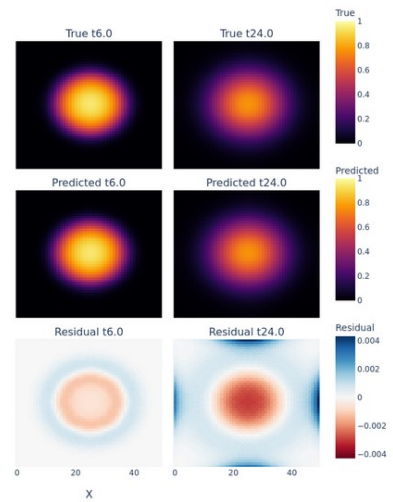
BrainPhys

$$\frac{\partial c}{\partial t} = D \nabla^2 c$$

$$\frac{\partial c}{\partial t} = z_X \nabla^2 c$$

where:

- $\frac{\partial c}{\partial t}$ is the time derivative of c , describing the accumulation and propagation of misfolded protein concentration.
- $D \nabla^2 c$ represents diffusion



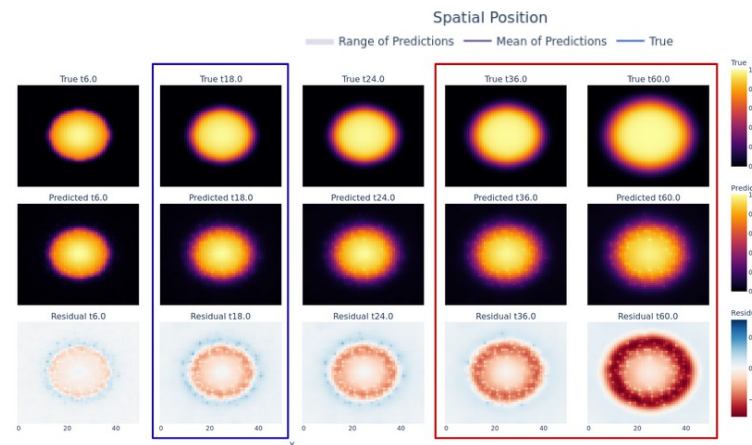
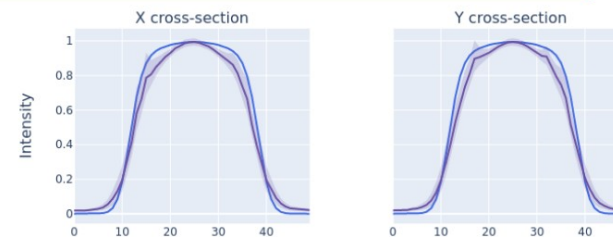
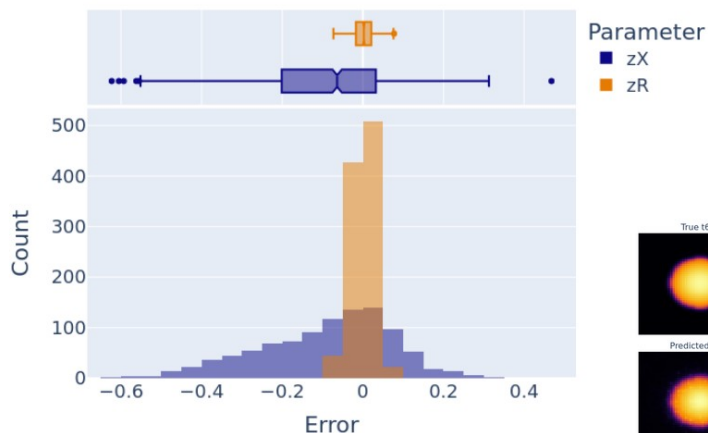
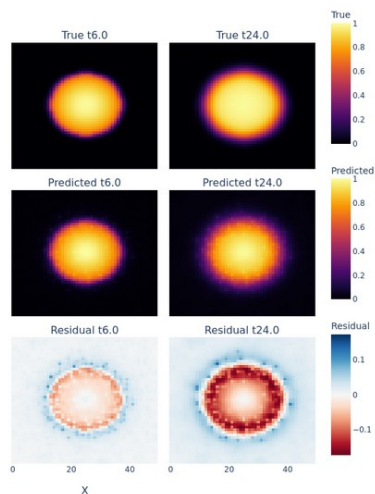
BrainPhys

$$\frac{\partial c}{\partial t} = D\nabla^2 c + rc(1 - c)$$

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Detecting model mis-specification

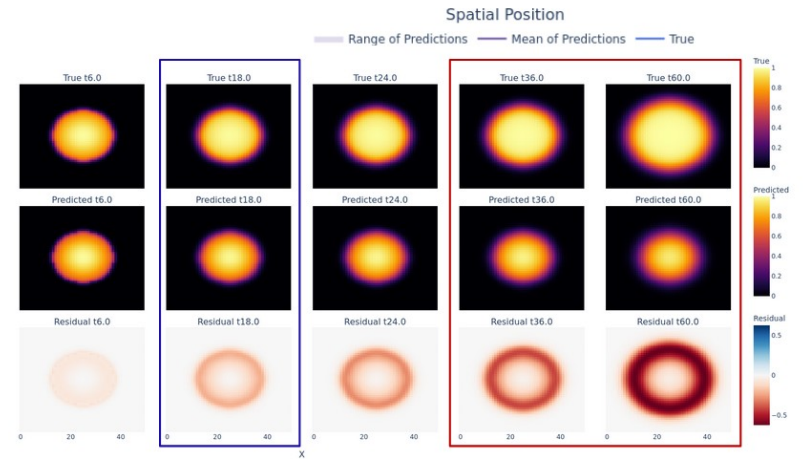
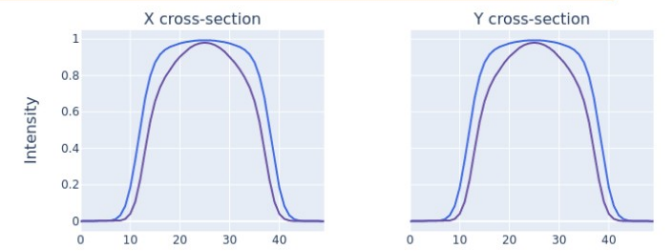
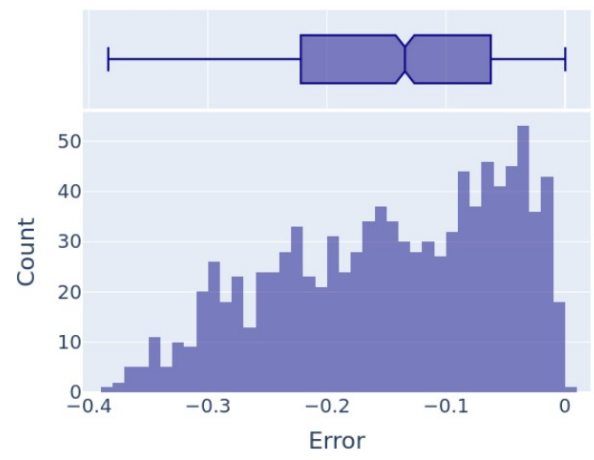
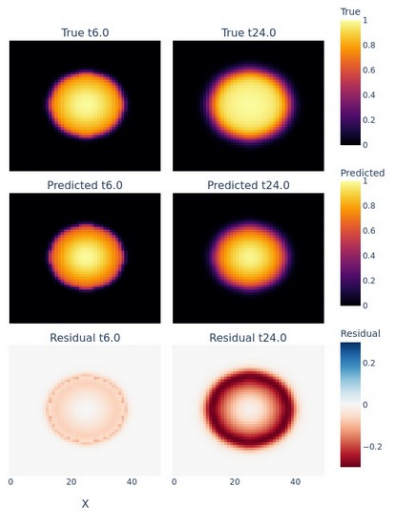
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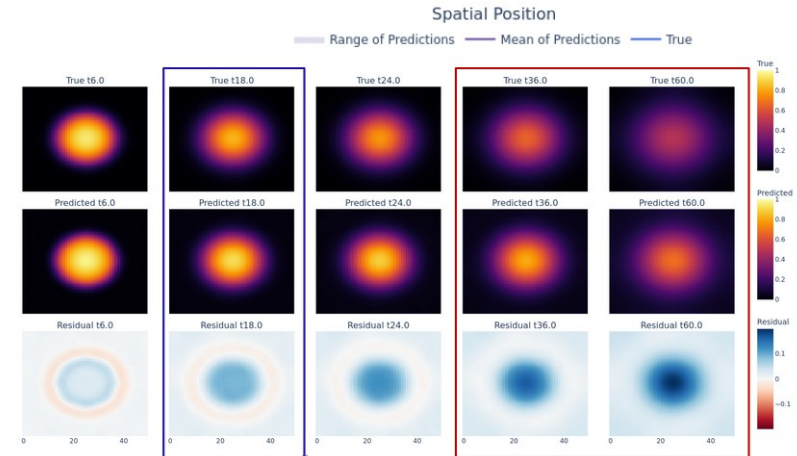
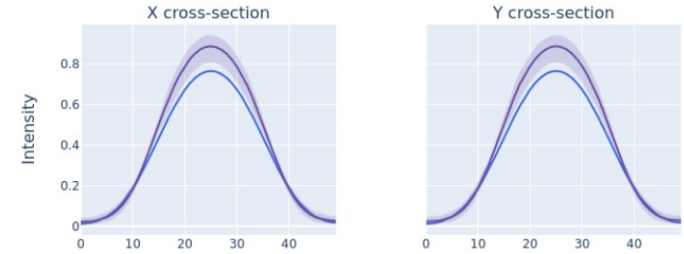
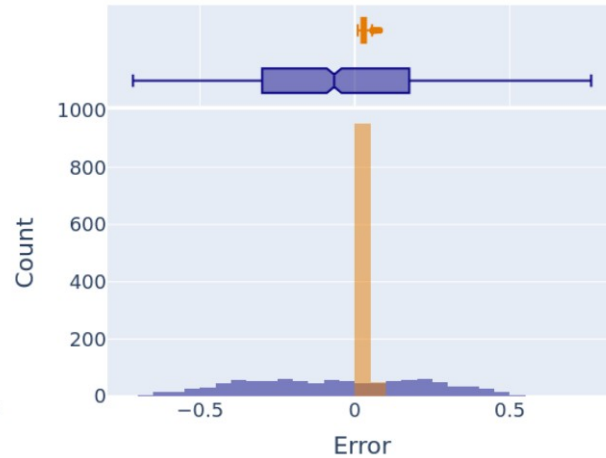
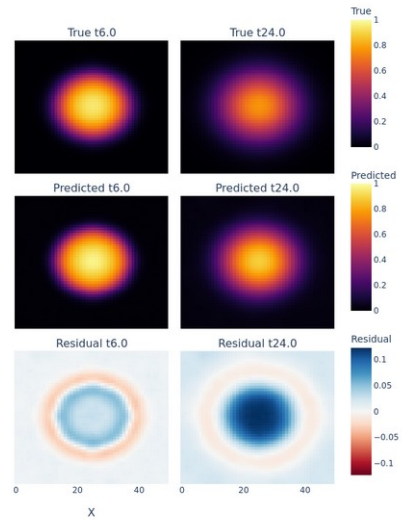
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Summary and next steps

- Probabilistic models can be used to learn hidden information in diseases
- Optimal transport formulation offers many benefits over standard maximum likelihood approaches
- Physics-guided/integrated/informed... machine learning gives flexibility
- But... identifiability, validation (ground truth?), assumptions, ...

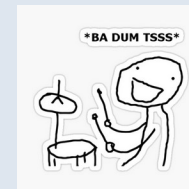
Many interesting theoretical avenues...

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Many interesting theoretical avenues...

Just need to pick the optimal route!



Backup: uncertainty

